

***Servo Drive MINAS-A4N
with Realtime Express (RTEX)***

Panasonic Corporation



200W 200V

Overview

Realtime Express (RTEX)

**Advanced Network to realize high-precise
real-time performance for Servo Control**



Concept

**High Performance
& Low Cost**

Simple

High Reliability

Easy Development

Features of *RTEX*

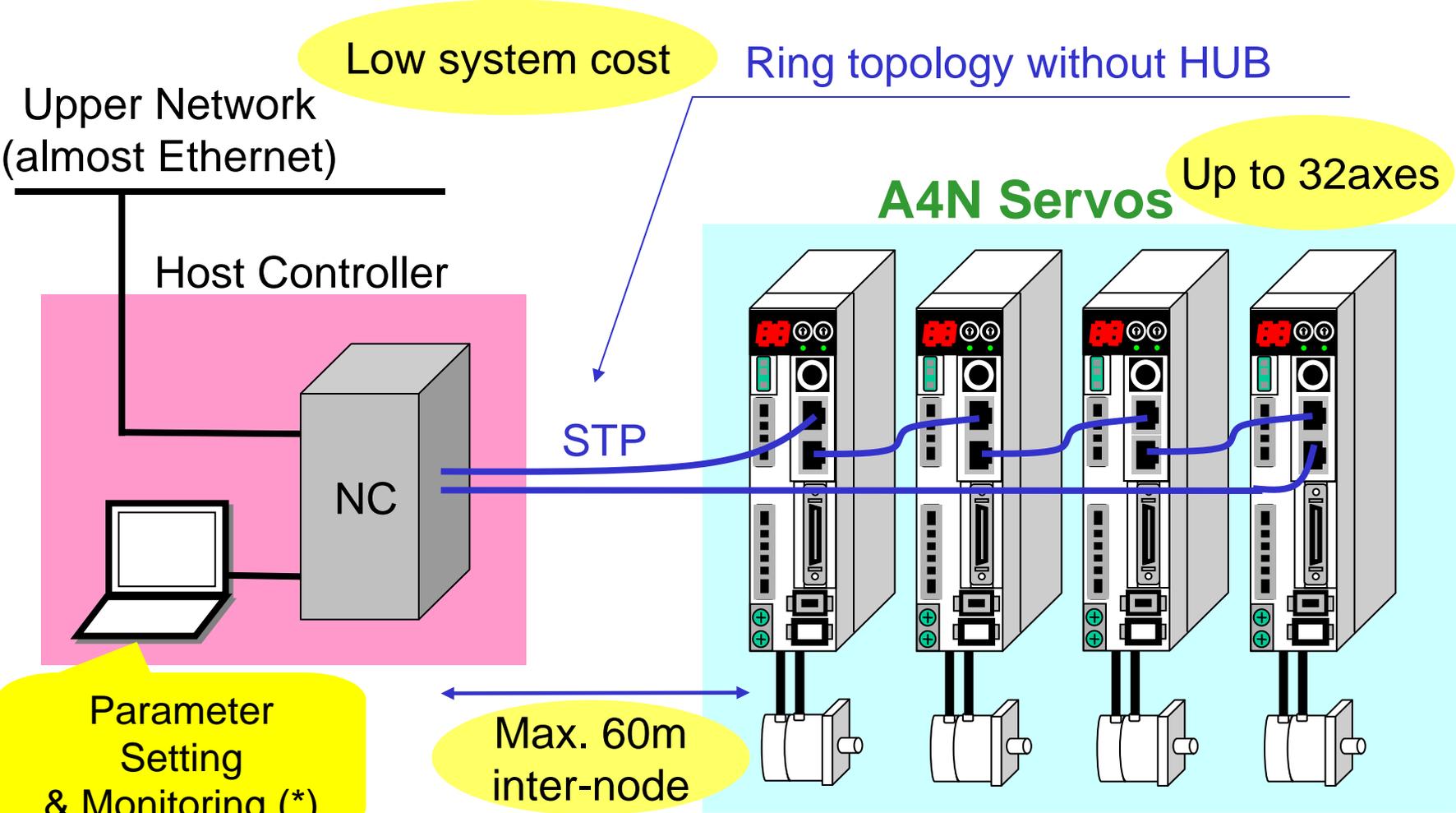
- **Real-time communication** based on 100BASE-TX
- **100Mbps Full duplex**
- **0.5ms cycle** with up to **32 axes** (*1)
- **Max. 60m length** inter-node cable
- **All axes fully synchronization** (*2) for interpolation
- **Parameter setting and monitoring**
- **Less wiring**
- **Low cost system** using shielded twisted pair cable
- **High noise immunity** (IEC61000-4-4 compliant)



*1: Depends on a controller specification.

*2: This sync algorithm is a patent.

System Structure

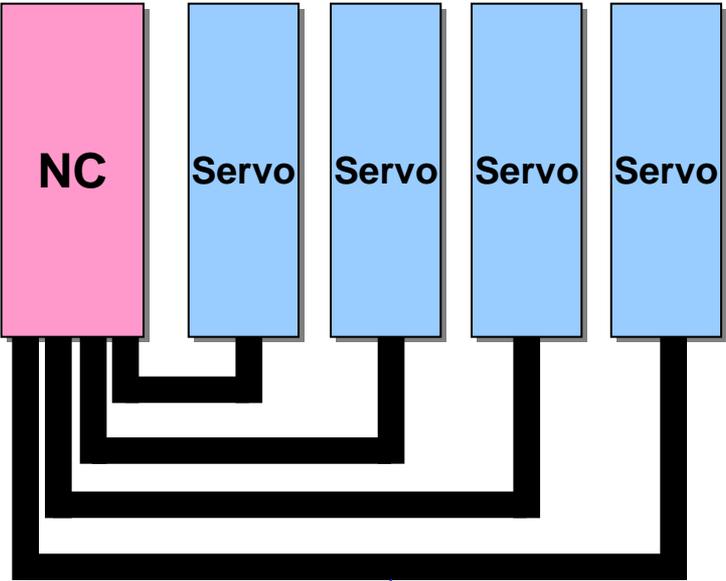


*: Depends on a controller specification

STP: Shielded Twisted Pair cable

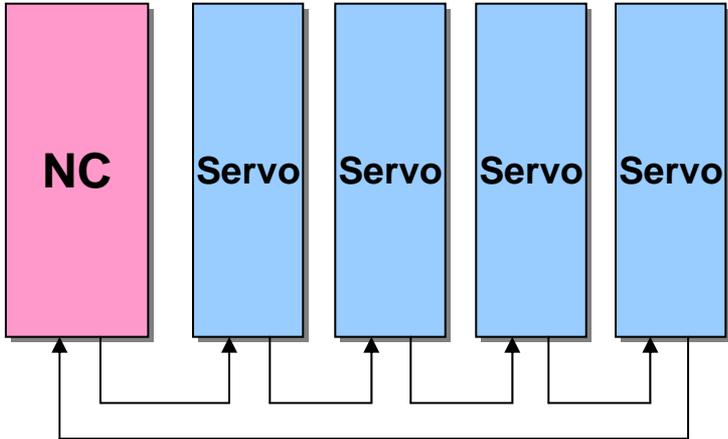
Less Wiring at Multi-Axes

Pulse I/F



Bundle of Many Wires

RTEX



Simple!

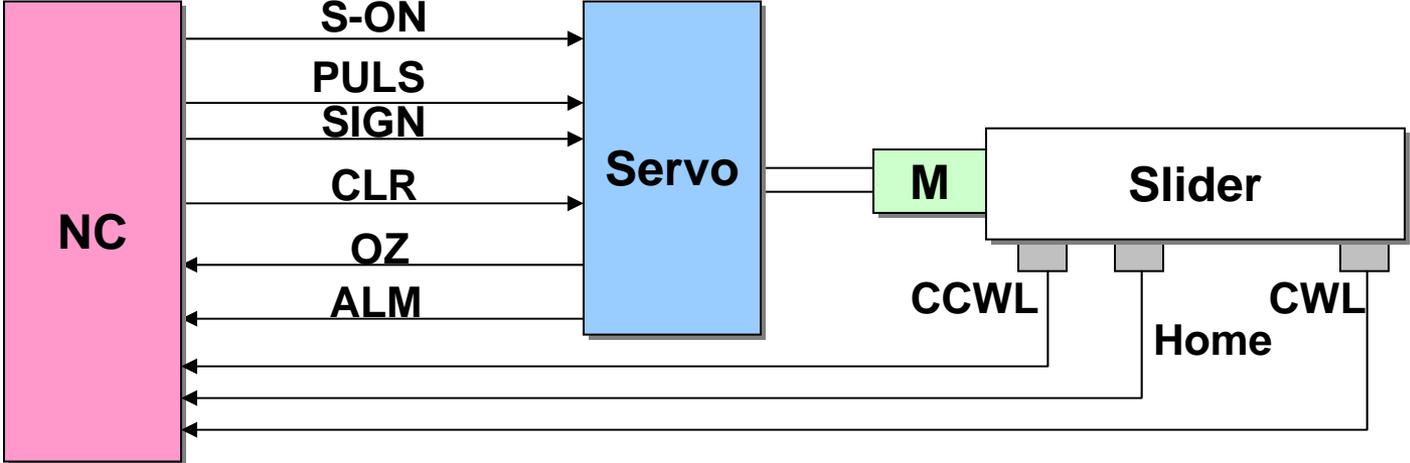
Reduced trouble with wiring

High benefit in distributed placing

Less Wiring at Single-Axis

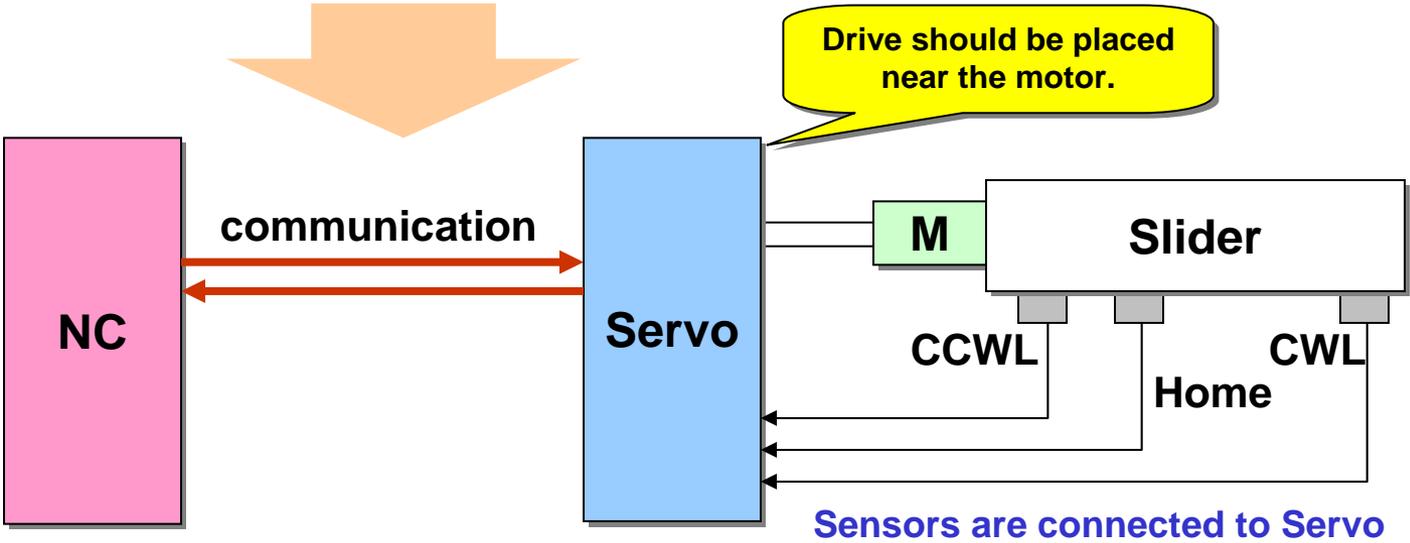
Pulse I/F

Many wires

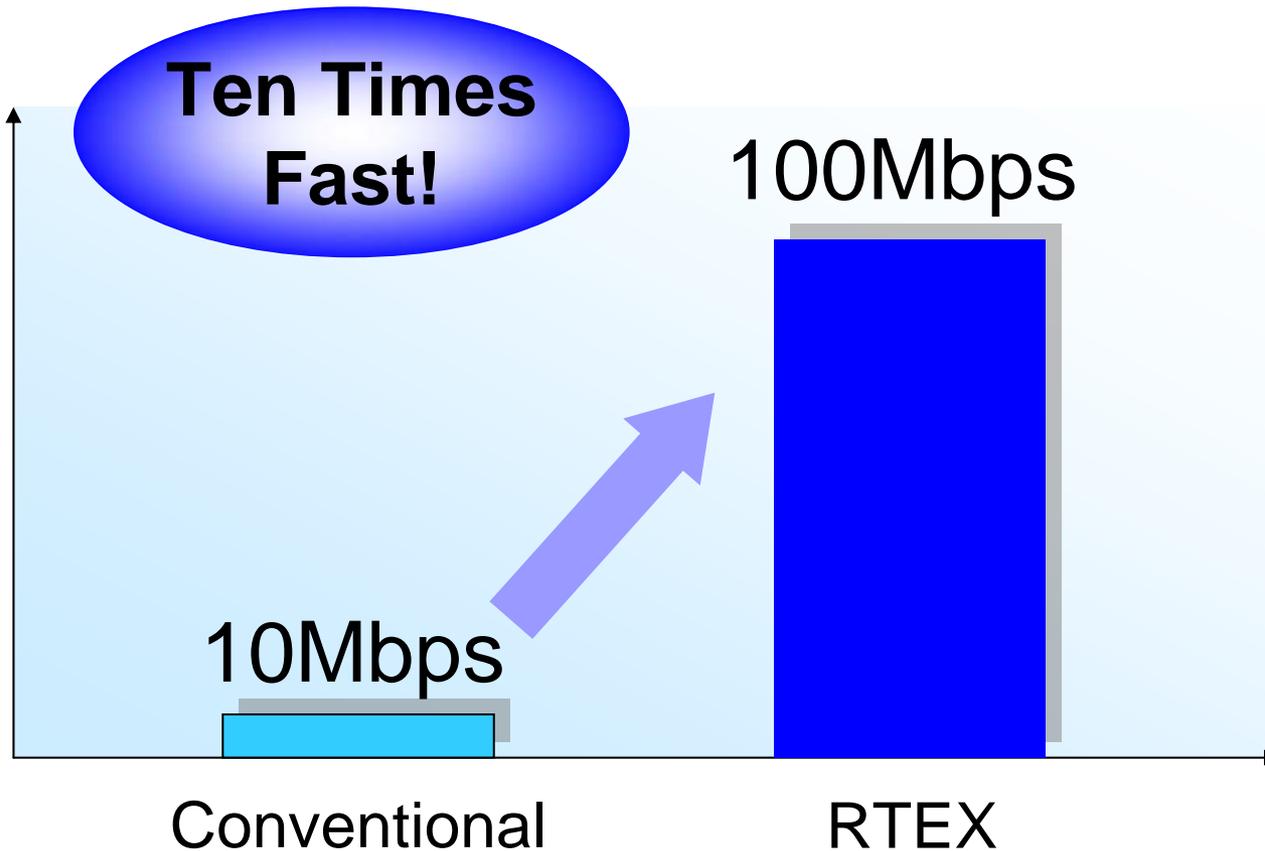


RTEX

Simple!

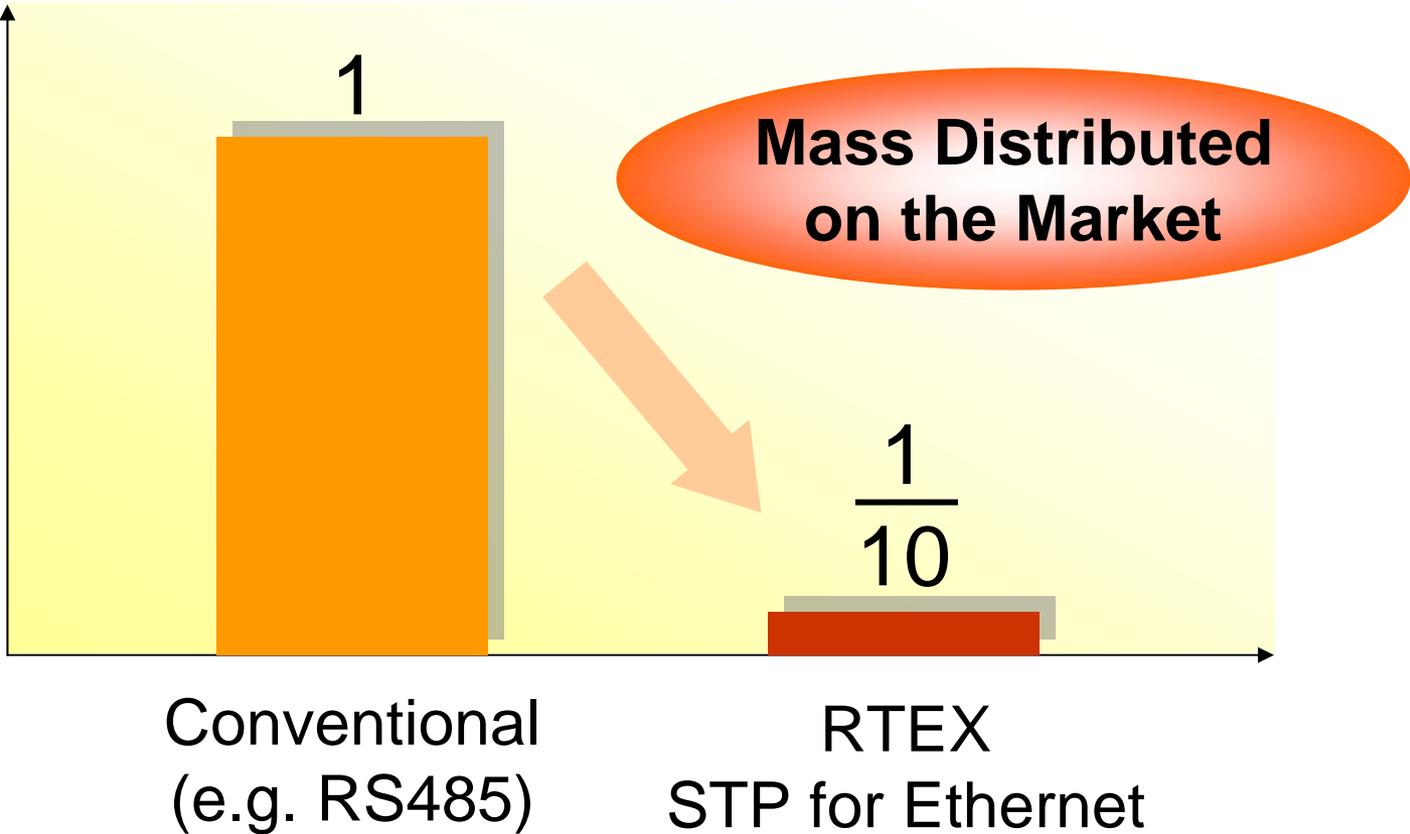


Ultra High-Speed



Using Low-Cost Cable

Cable Cost Ratio

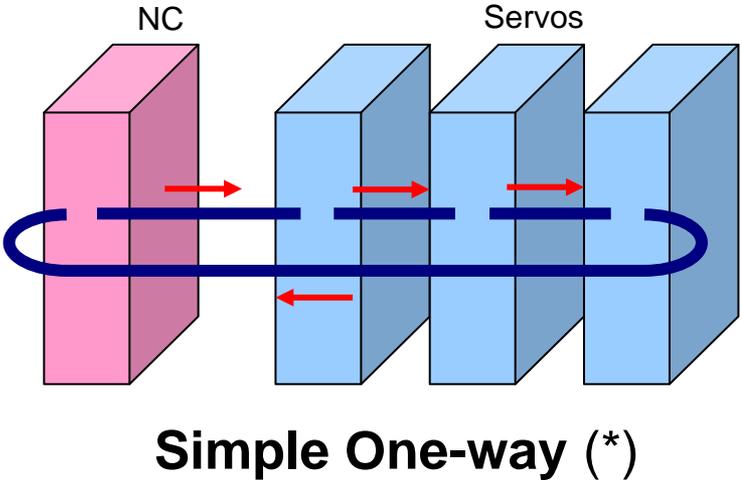
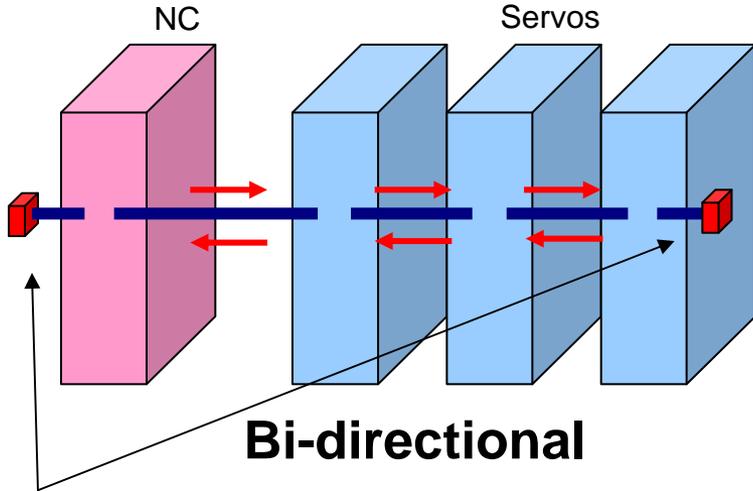


Note: An example of 1m length.

Simple Ring Topology

**RS485
(LINE)**

**RTEX
(RING)**



Termination
Resistor

A Trouble

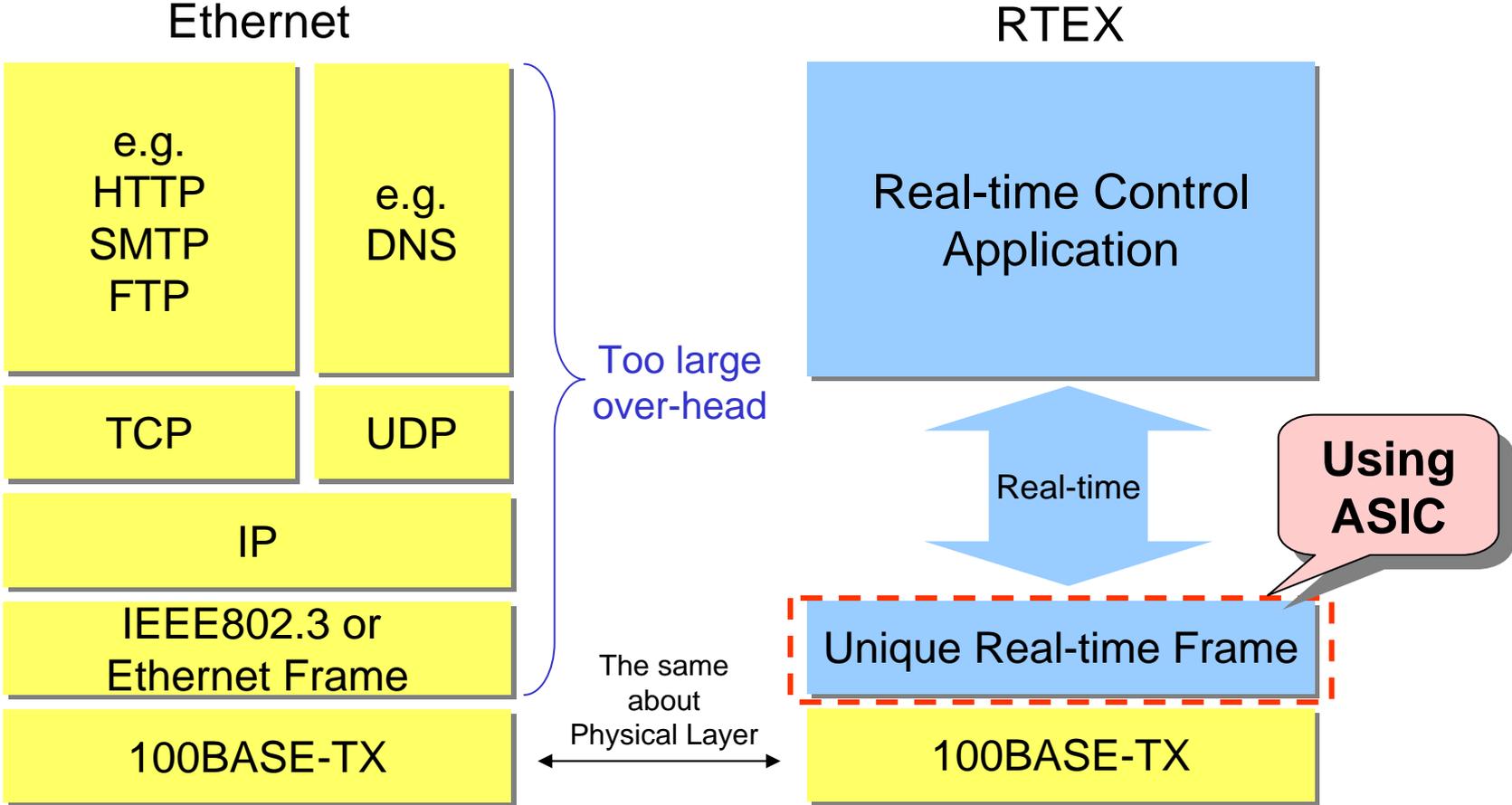
**High Efficiency & Reliability
by Simple Data Flow**

*: No cross-talk.

Features of *RTEX*

Difference from Ethernet

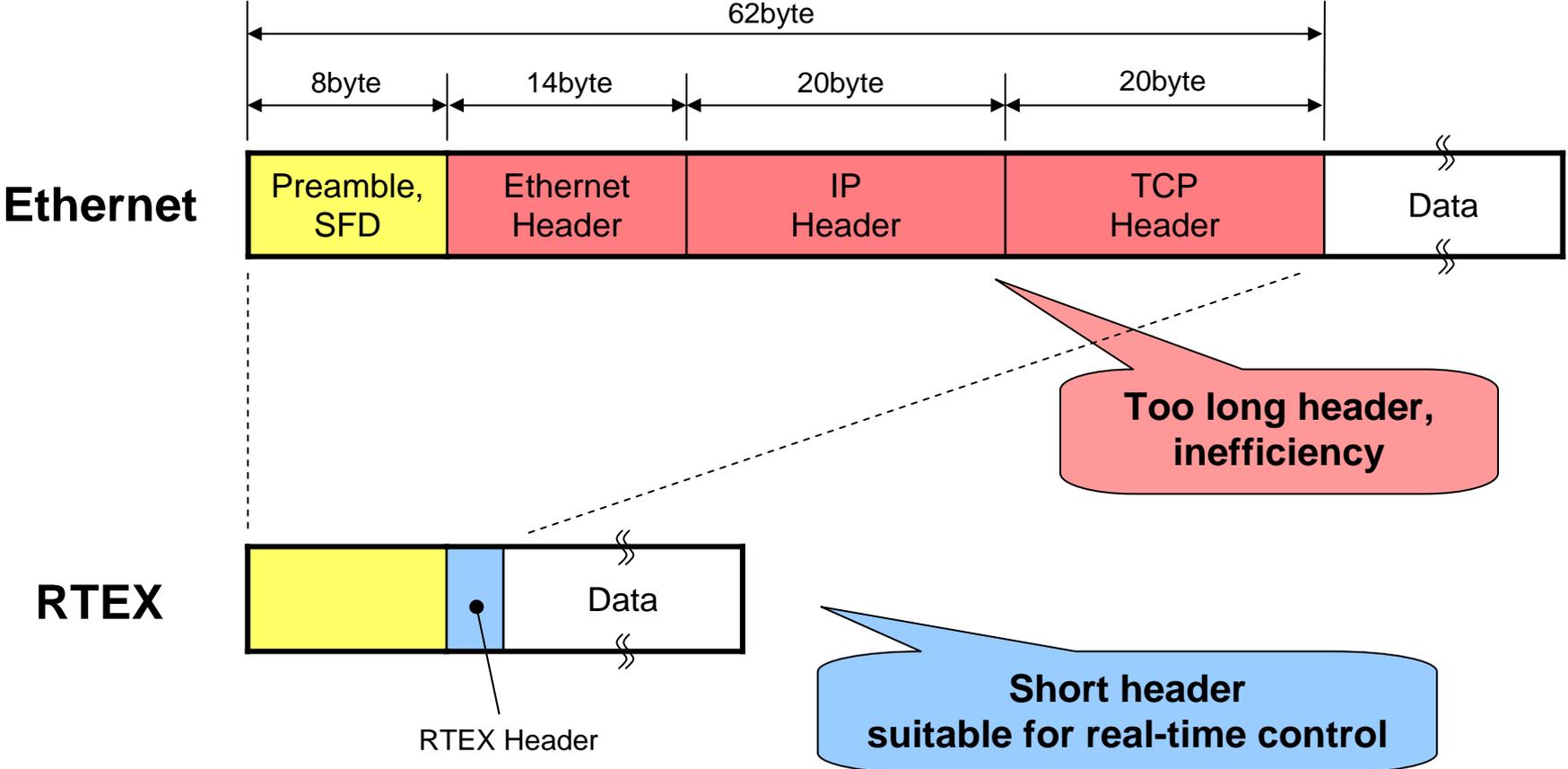
Upper layer optimized for servo control



Note: Ethernet is a registered trademark of Xerox corporation.

Efficient Frame

Simplified frame to realize high-speed real-time control



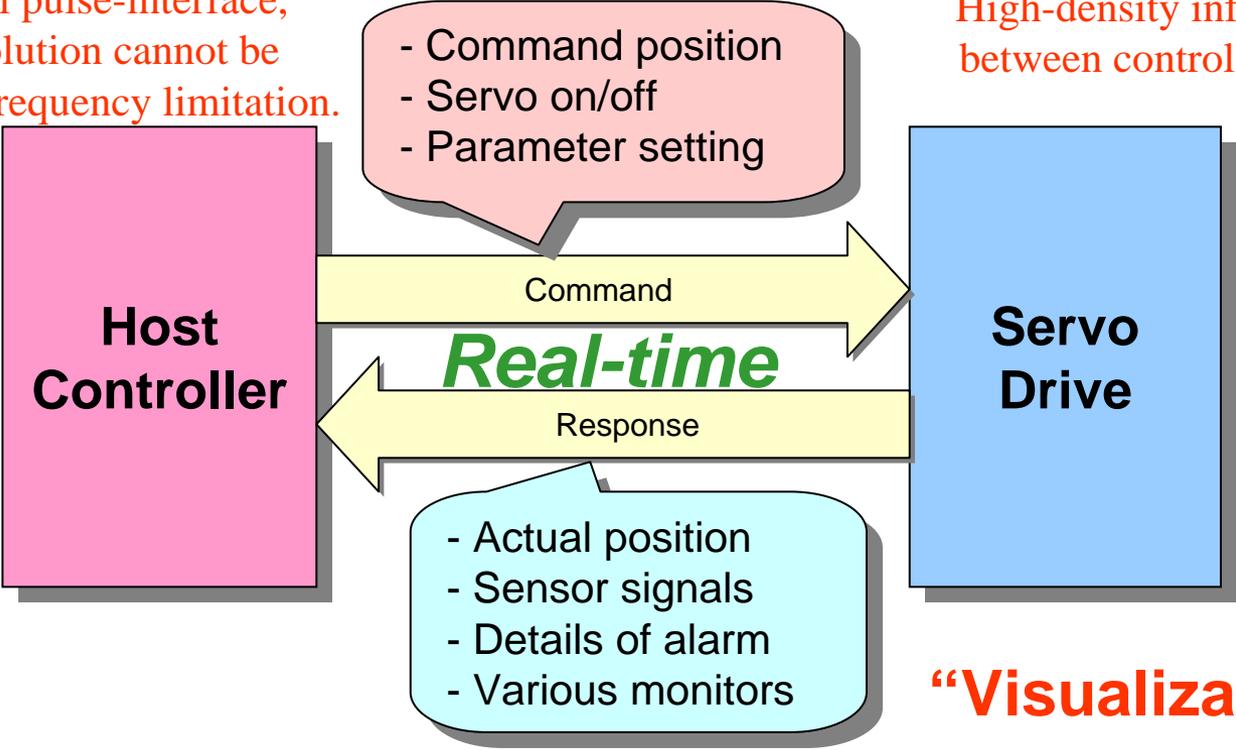
Real-time Communication

Fast and High Resolution Motion Command

In conventional pulse-interface, command resolution cannot be increased due to frequency limitation.

Parameter Setting and Monitoring

High-density information links between controller and servos.



“Visualization”

Isochronous among Axes

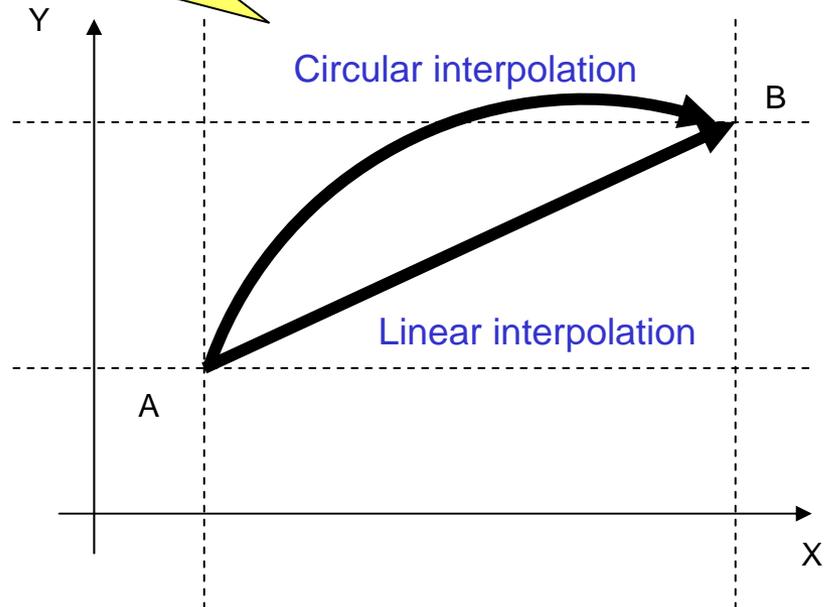
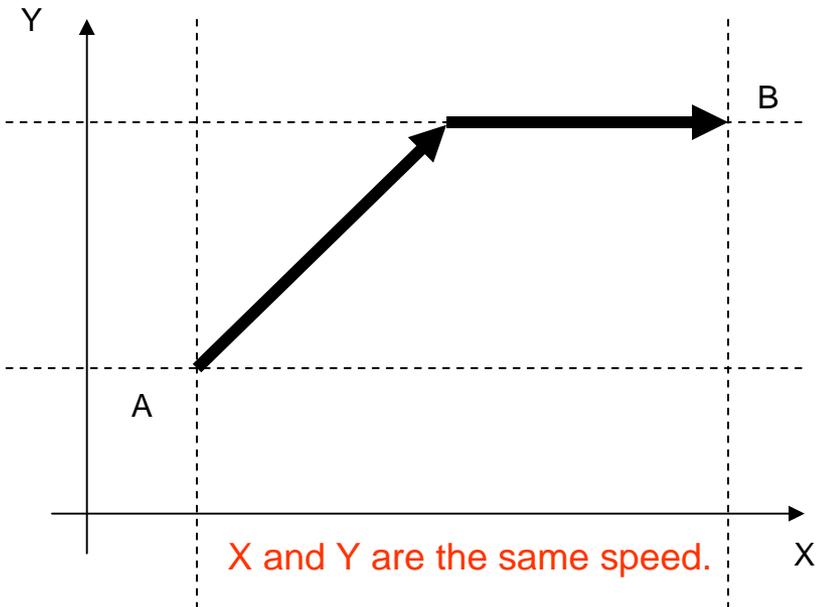
PTP

Point To Point

Isochronous enables CP.

CP

Continuous Path



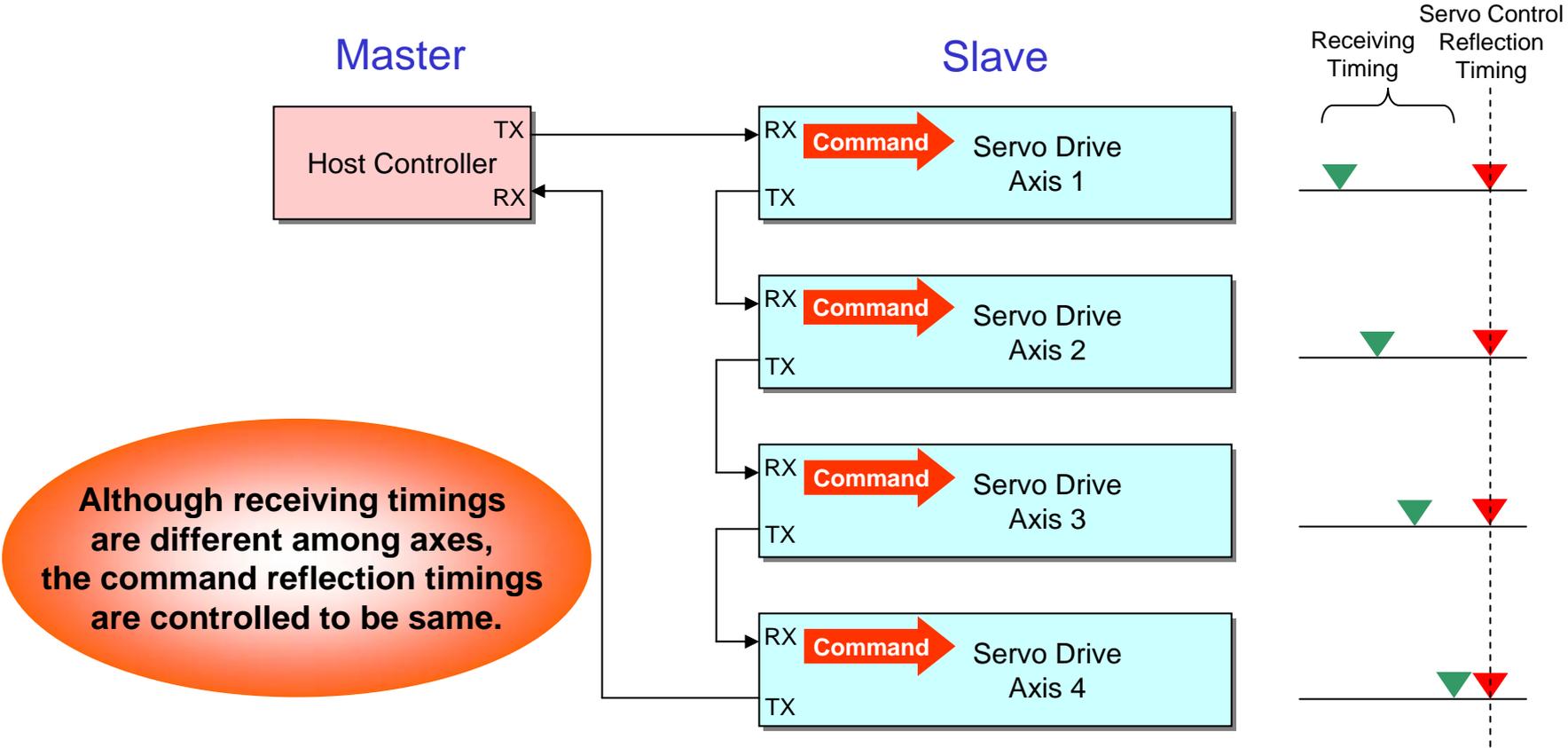
- Separately positioning
- Not corresponding Start/Stop timing between X and Y

- Synchronized positioning
- Corresponding Start/Stop timing

Note: CP control depends on a controller specification, and does not perform with only servo drive.

Isochronous transmission

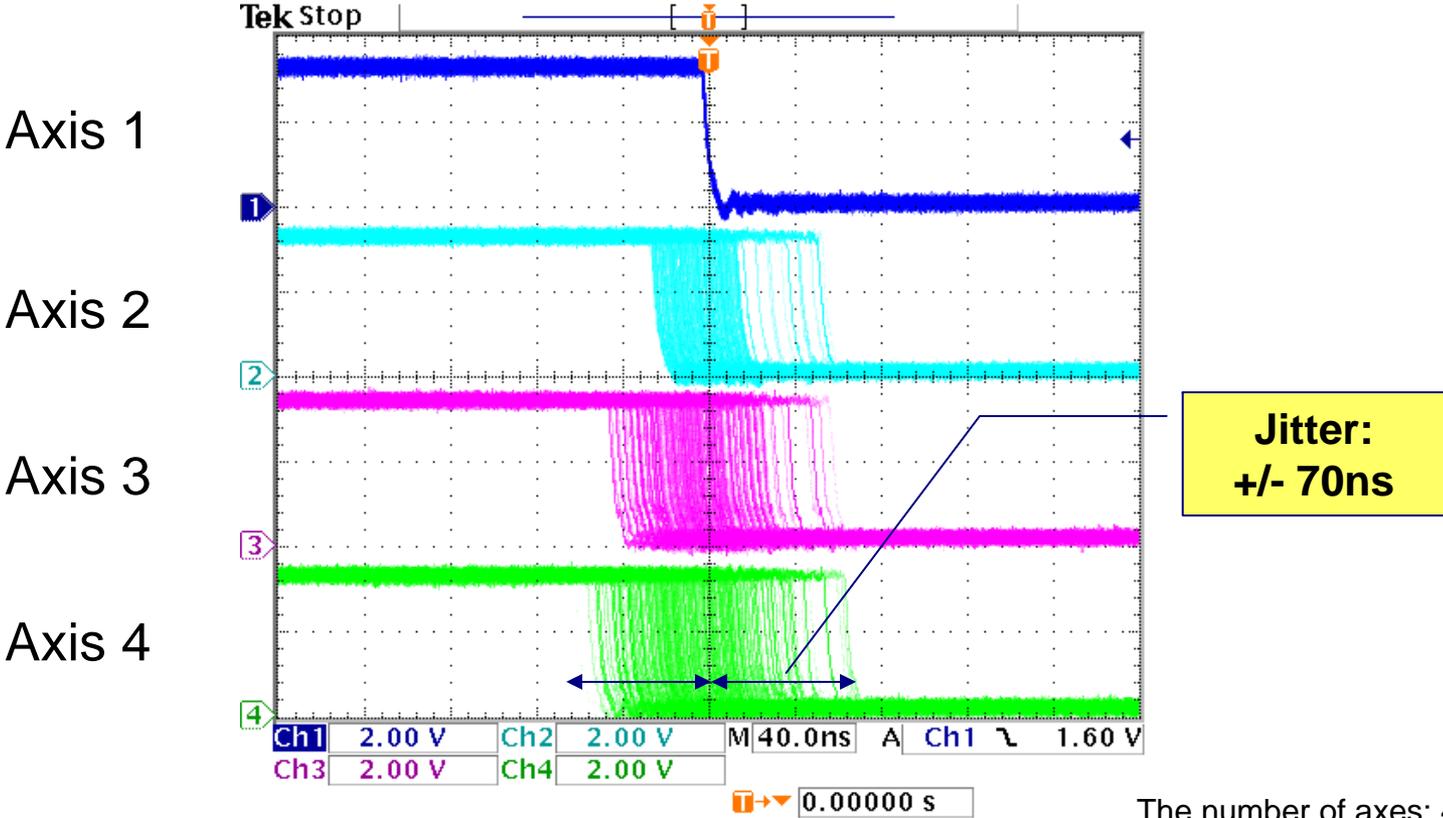
At the same time, commands are reflected in all servo drives.



Although receiving timings are different among axes, the command reflection timings are controlled to be same.

Isochronous Accuracy

Signals to start servo calculation inside each drive



Note: Generally, jitter less than 1us is ideal.

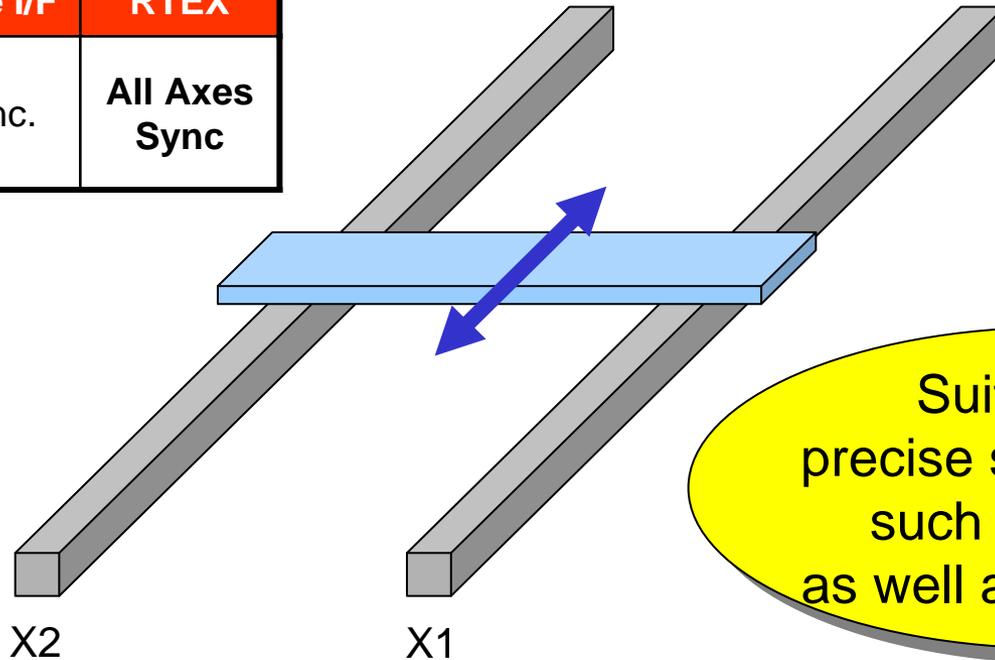
The number of axes: 4
Cable length inter-node: 0.3m

Fully Synchronization

With a unique algorithm (patented), NC is synchronized with all servo controls (position, velocity, current, PWM).

Improvement of sync precision among axes!

	Pulse I/F	RTEX
Servo Control	Async.	All Axes Sync

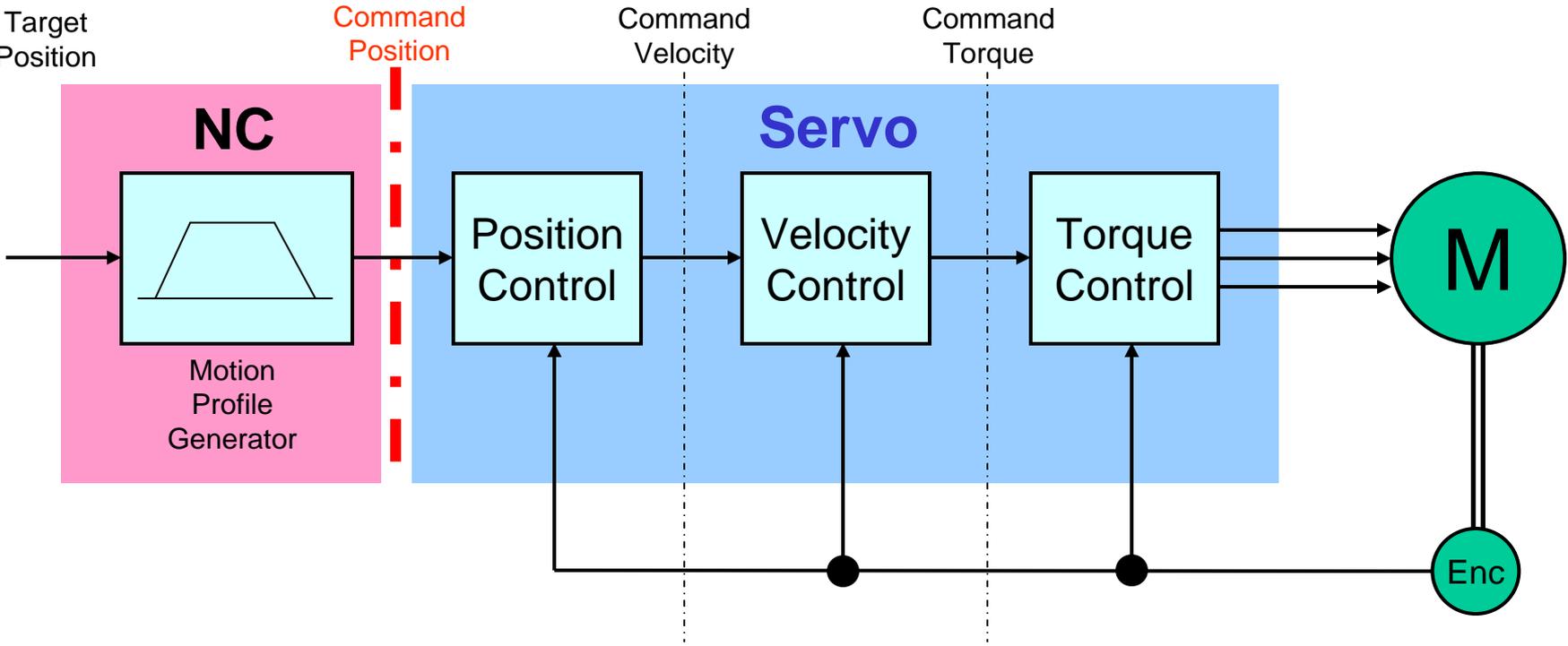


Suitable for precise synchronizing such as a gantry as well as CP control.

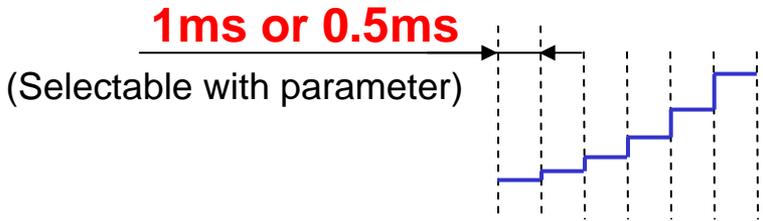
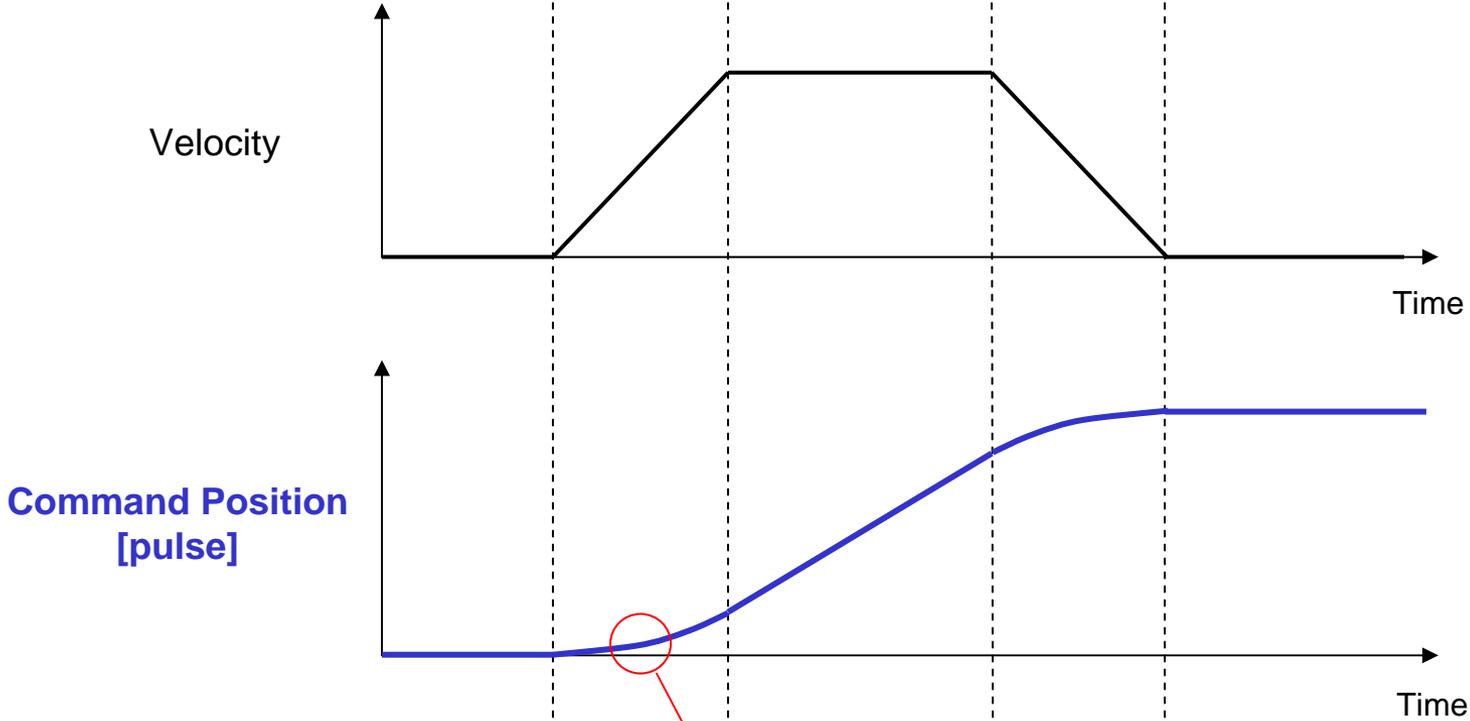
Interface and Com. Cycle

Position command with 0.5ms com. cycle

Shorter delay of transmission makes high servo performance.



Interface Data

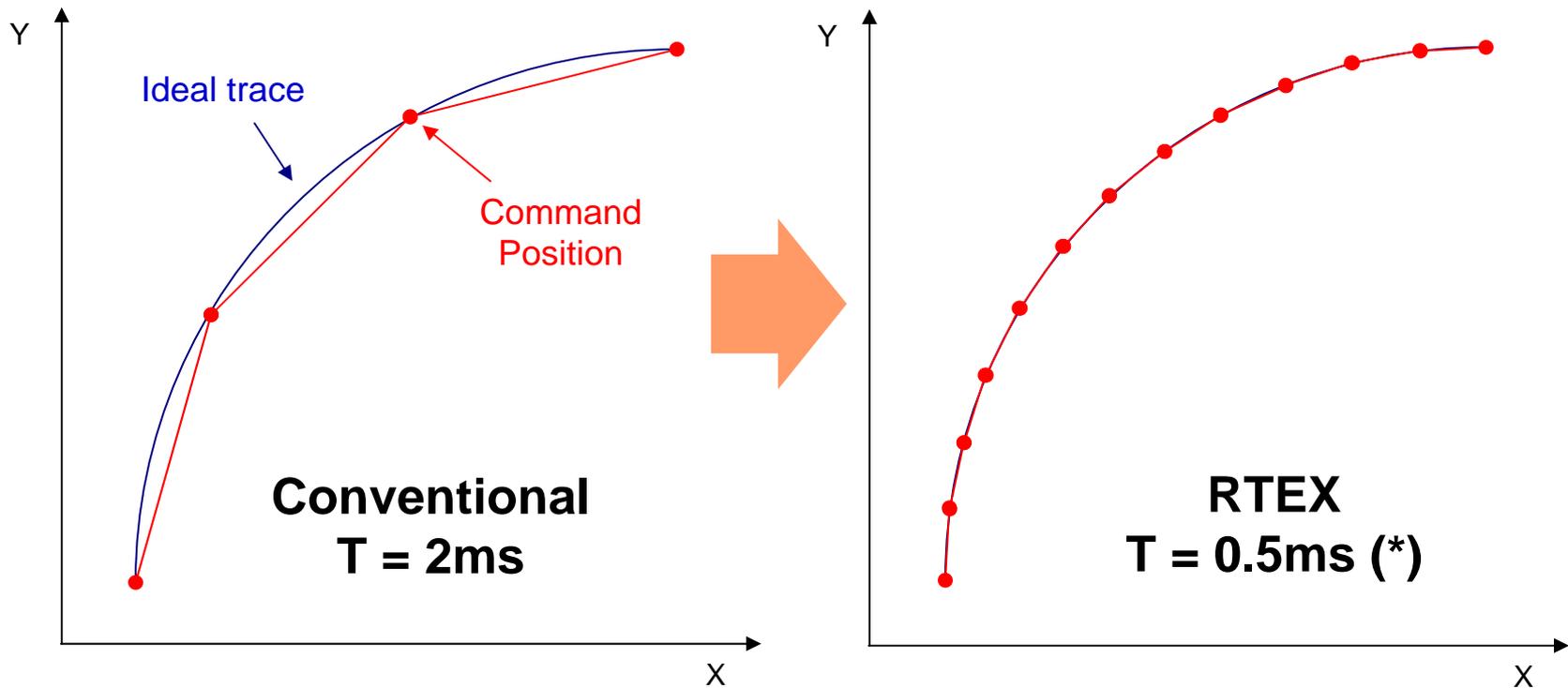


Absolute (not incremental) value must be used.
Default polarity: + → CCW, - → CW

Shorter Update Period

More Precisely on High-speed CP control

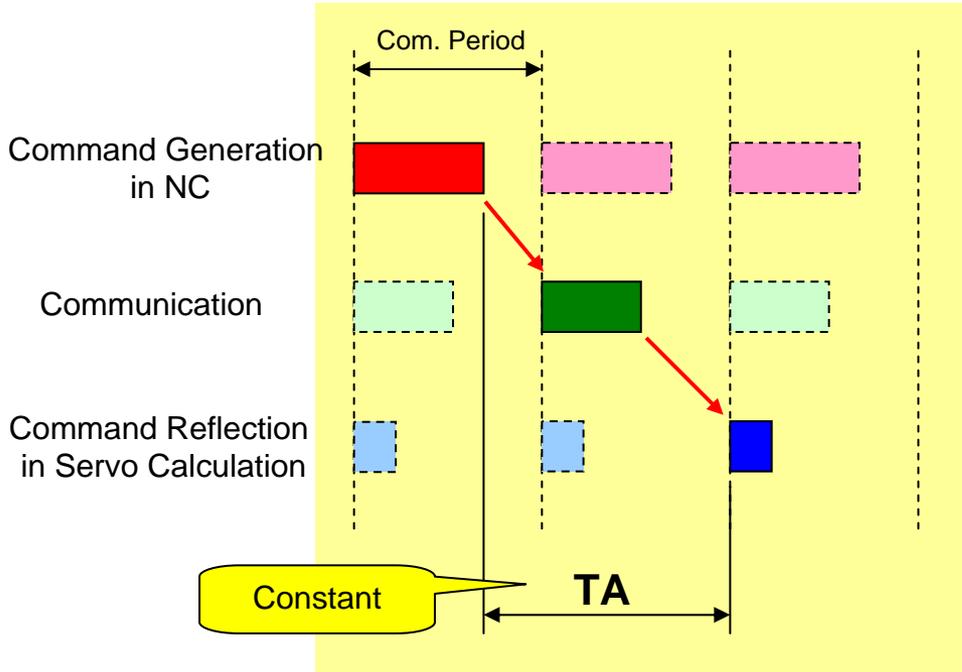
Micro circular interpolation (e.g. Dispenser)



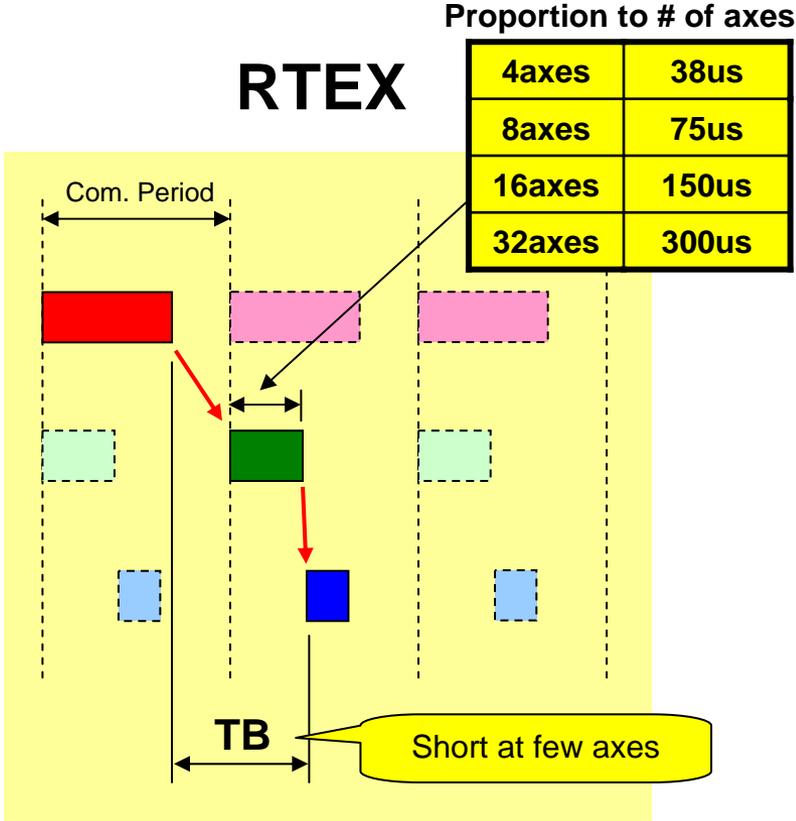
*: Data update period depends on controller specification, and is either 1ms or 0.5ms.

Shorter Transmission-Time

Conventional System



RTEX



TA > TB

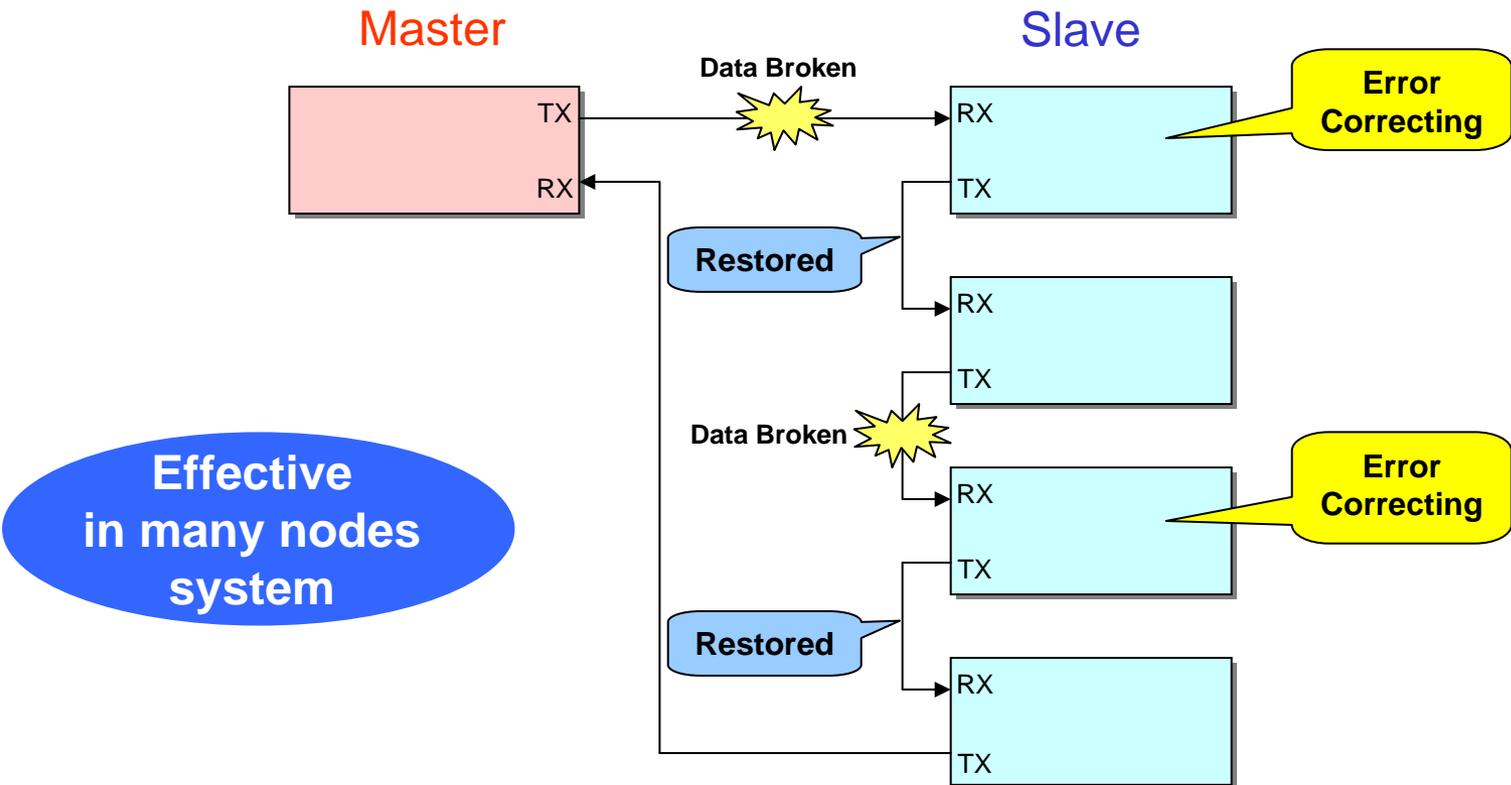
Command is applied to the servo control as soon as after all axes receiving.

Note: The above shows a case when the data update is done with the same period as the communication.

Error Correction

Error corrected at going through nodes.

▶▶▶ **Strong Noise Immunity**



Note: Because of limitations of the error correct ability, there is a case where it cannot restore broken data.

Specifications of *RTEX*

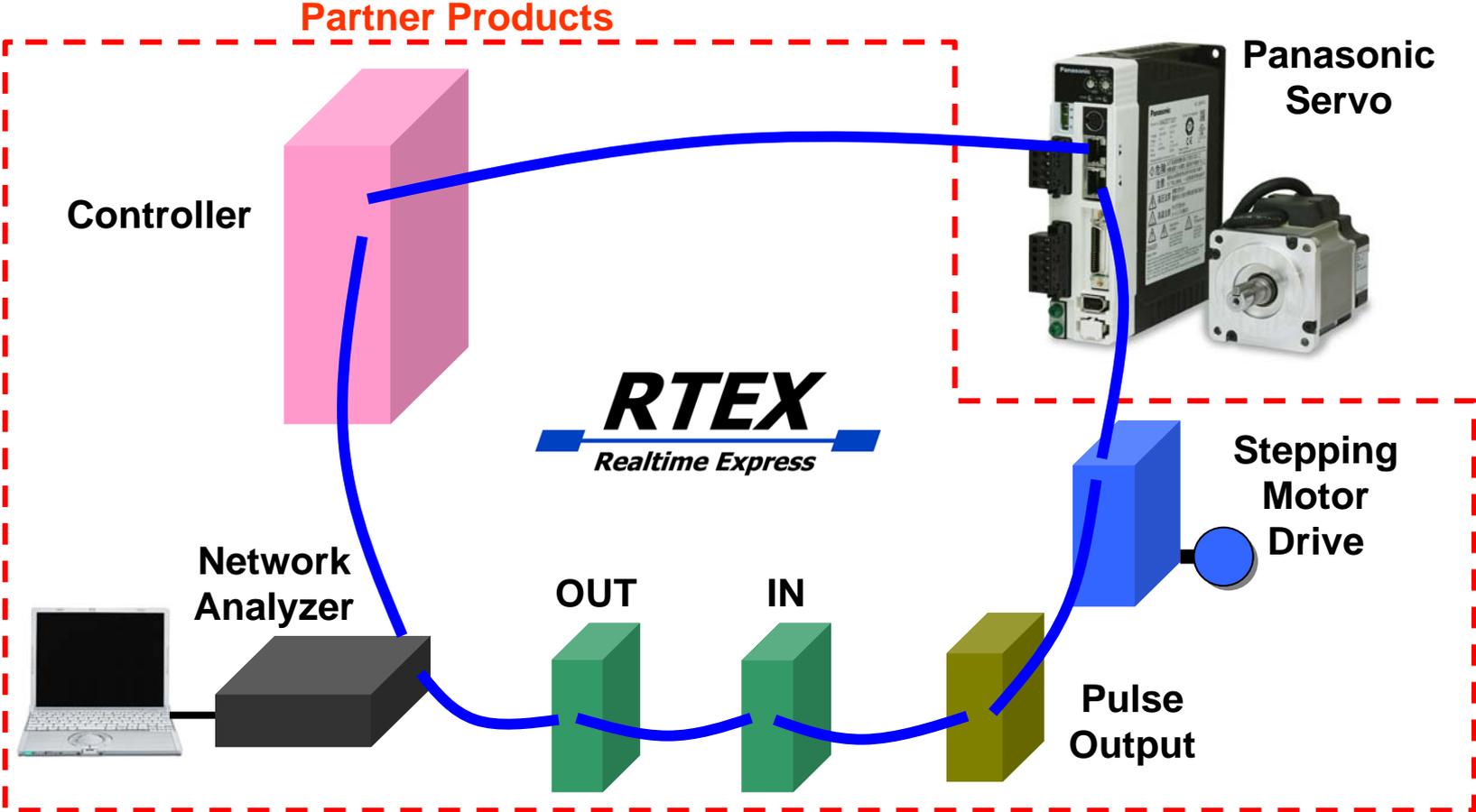
Item	Specifications
Speed	100Mbps
Physical Layer	100BASE-TX full duplex (by IEEE 802.3u)
Cable	Shielded Twisted Pair (TIA/EIA-568B CAT5e or more)
Topology	Ring
Isolation	Pulse Transformer with common-mode choke
Connector	RJ45
Cable Length	Inter-node: Max. 60m, Total: Max. 200m
Noise Immunity	2.5kV over, IEC61000-4-4 compliant
Com. Cycle (*)	0.5ms (data update: 1ms or 0.5ms)
Number of Axes (**)	Up to 32
Motion Interface (*)	Position Command

* Note: For standard model of A4N

** Note: Depending on specification of host controller

Collaboration

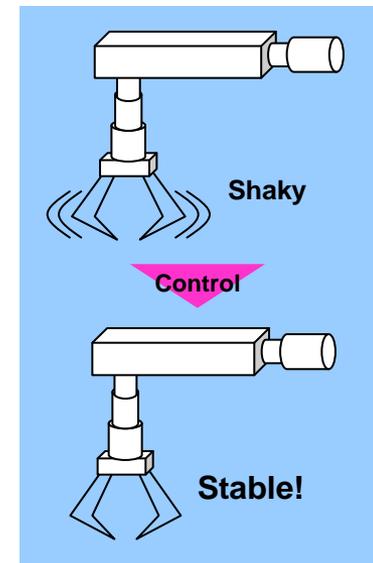
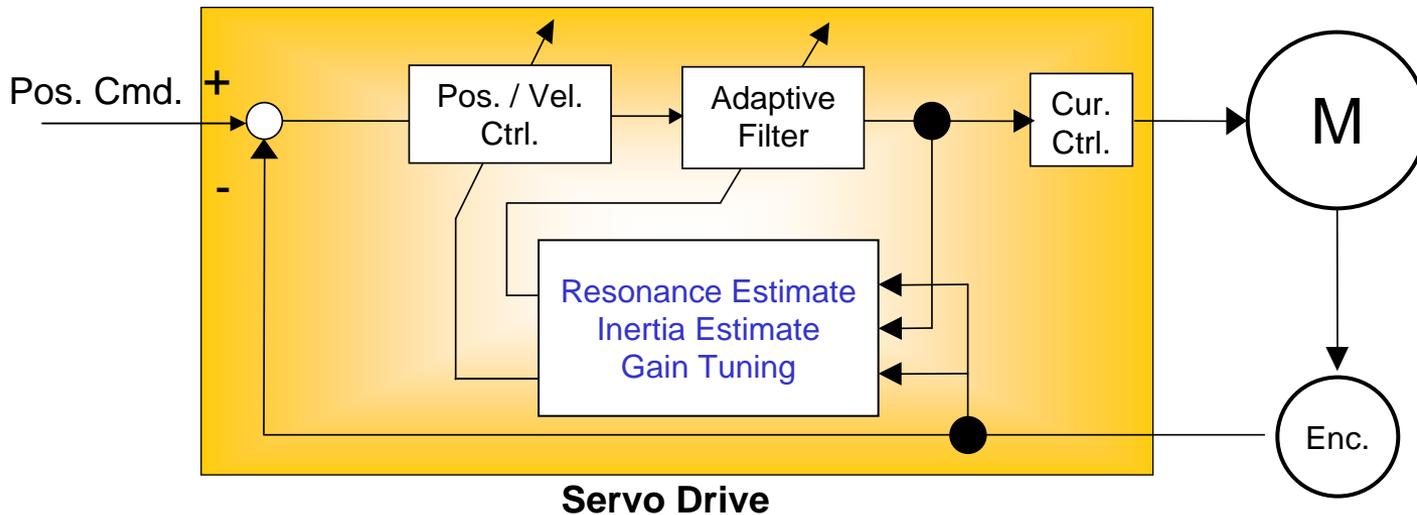
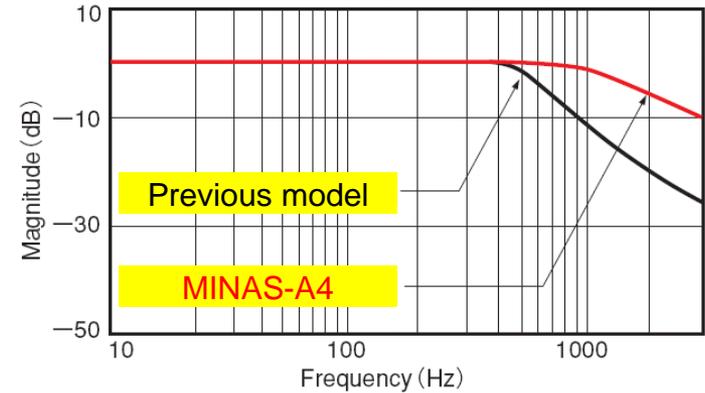
Products except servo are provided by partners.



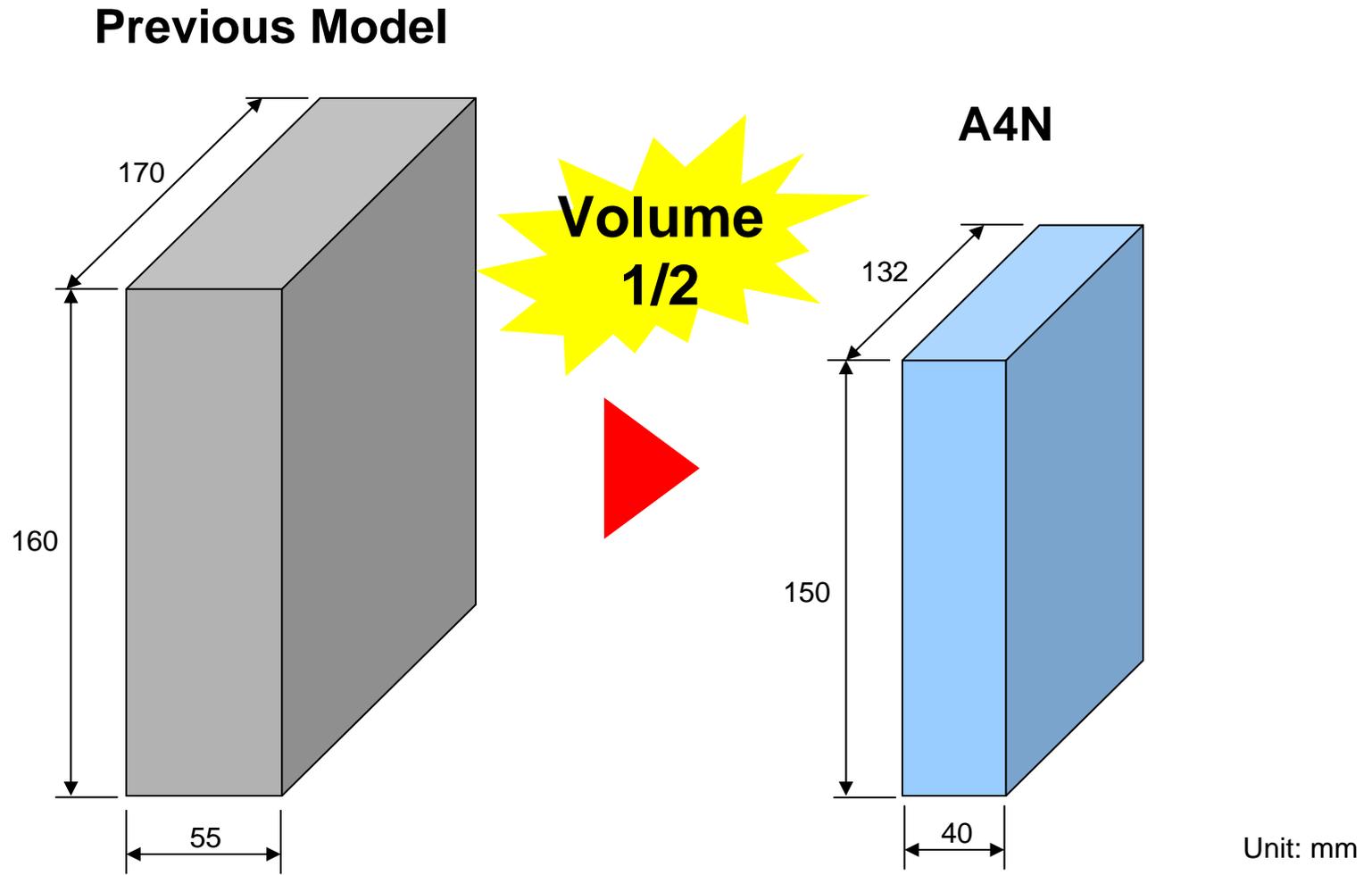
Features of Servo

Features of A4 (Base of A4N)

- 1000Hz velocity response
- Advanced real-time automatic gain-tuning
- Vibration reduction control



Compact



Note: Comparison with B series (200W, 200V)

Setting Tools (Optional)

Setup Software
"PANATERM"
DV0P4460

- Parameter Setting
- Monitoring
- Wave Form
- Freq. Analyzing etc.



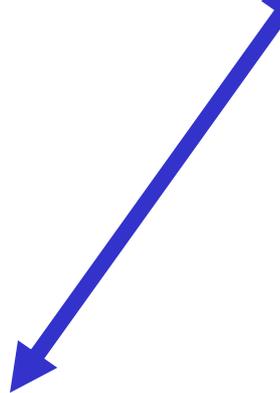
Connect with RS232(X4)



Alternative

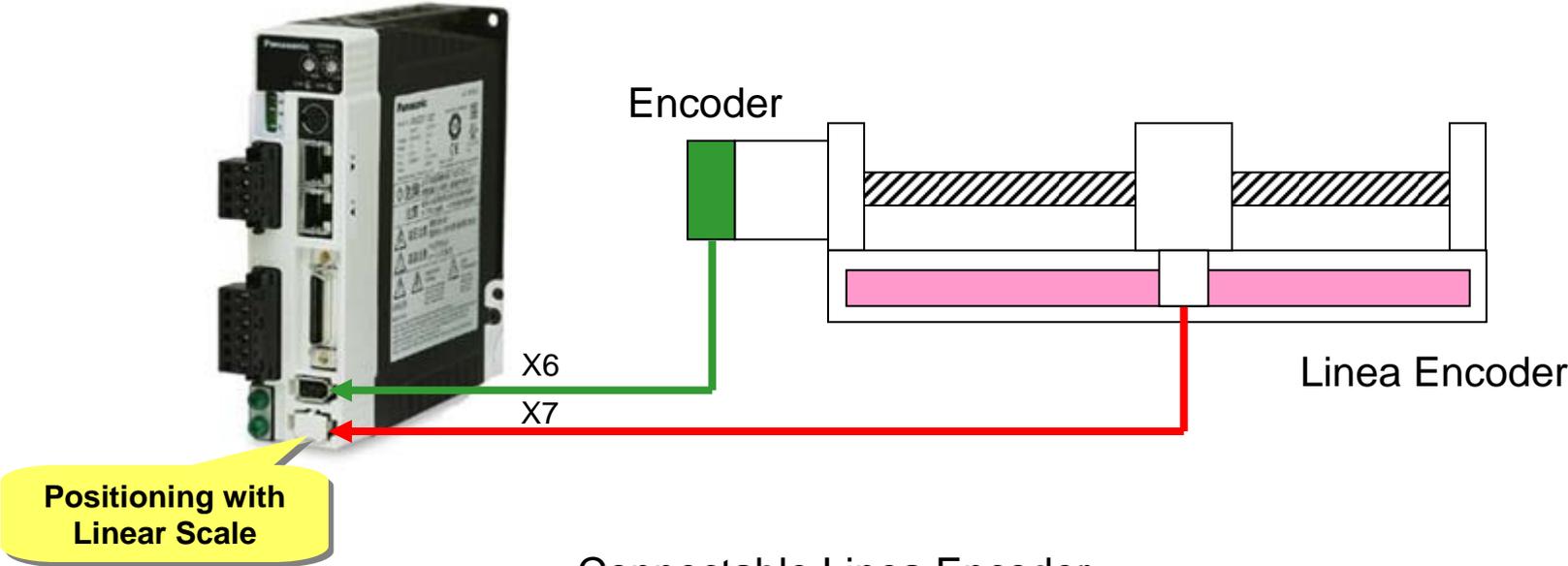
Handy Console
DV0P4420

- Parameter Setting
- Monitoring
- Jogging etc.



Full-Closed Control

High precision full-closed control system



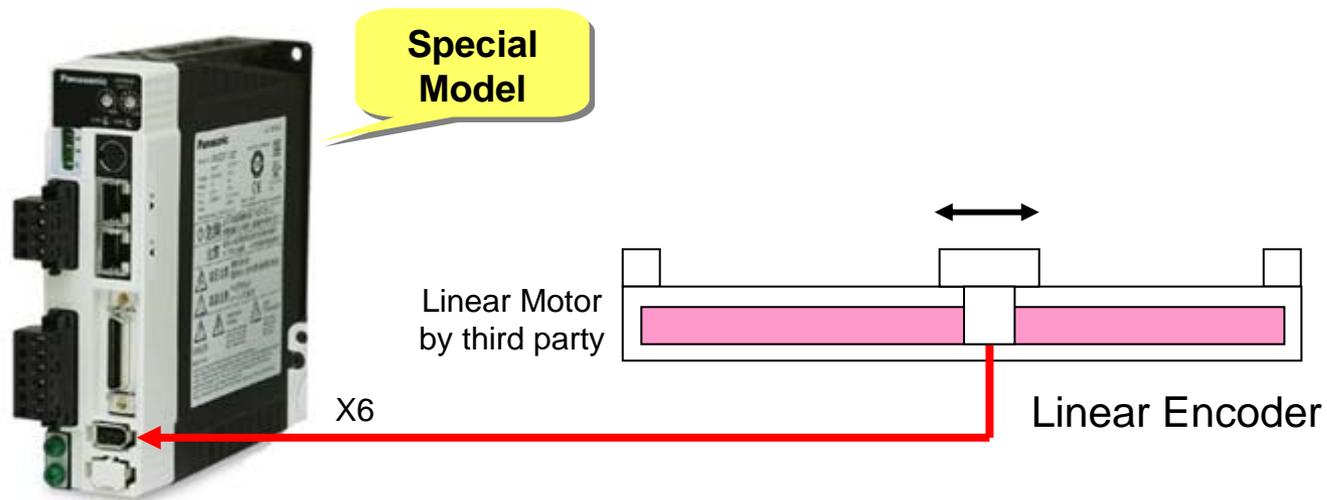
Connectable Linea Encoder

	Mitsutoyo		Sony Manufacturing Systems		
	AT573A	ST771A / ST773A	SR75 / SR85	SR77 / SR87	SL710 + PL101-RP
Type	Absolute	Absolute	Incremental (*)	Absolute	Incremental (*)
Resolution	0.05um	0.5um / 0.1um	0.05 to 1um	0.05 to 1um	0.1um

Note: For incremental, the special model of servo is needed.

Linear Motor Drive

Special servo drive for linear motor can be provided.



Notes:

- Panasonic do not provide linear motor.
- The linear encoder is the same as for full-closed control.
- Because of limitations of servo drive, the combination of resolution and max. speed are as follows:
 - max 2m/s at 0.05um
 - max 5m/s at 0.5um

Compliance

- UL, cUL
- TUV
- CE

EMC Directive

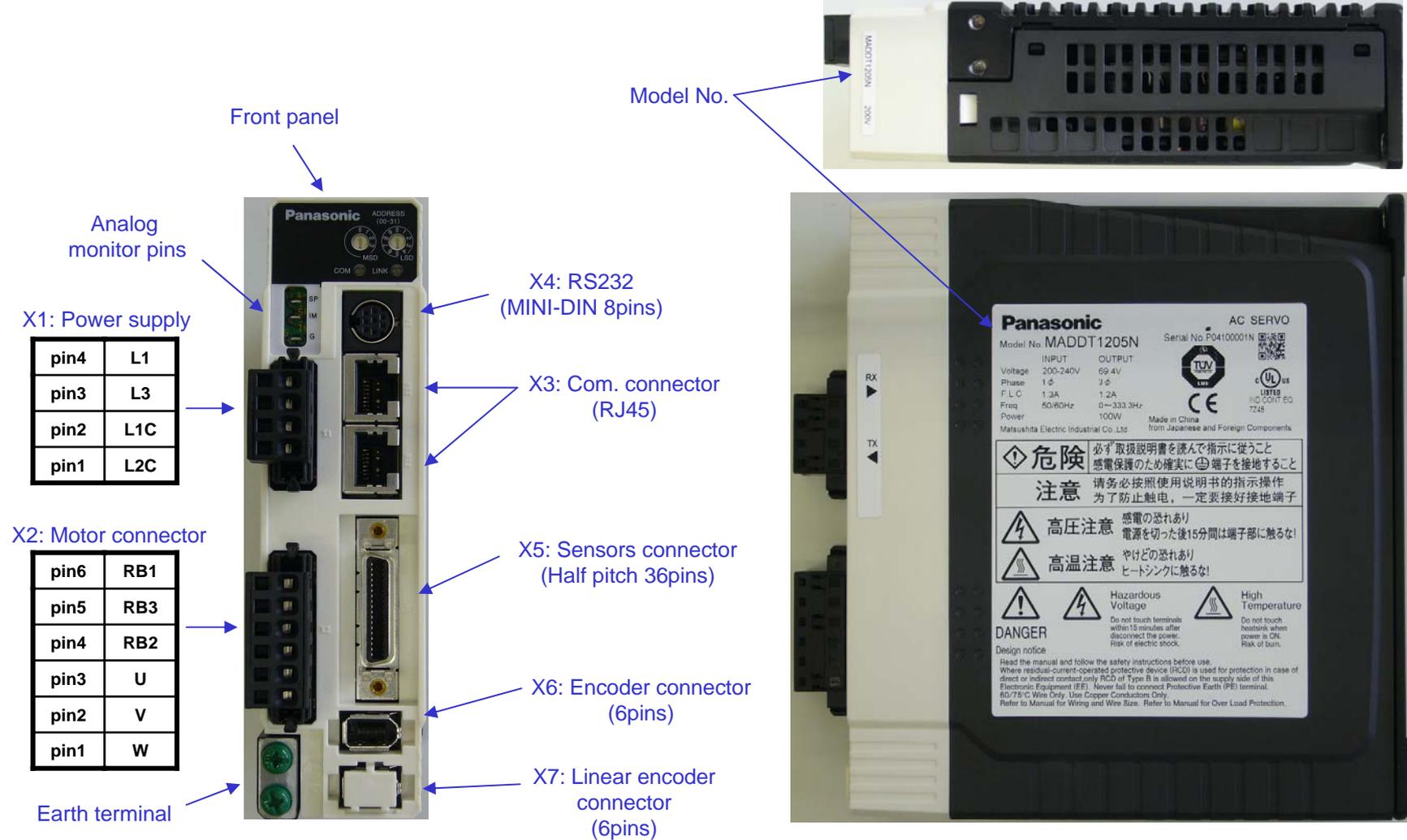
EN55011	Terminal Disturbance Voltage	group 1, class A
	Radiated Electric Field Strength	group 1, class A
IEC61000-4-2	Electrostatic Discharge	8kV
IEC61000-4-3	Radiated Susceptibility	10V/m
IEC61000-4-4	EFT/Burst	2kV
IEC61000-4-5	Surge	2kV
IEC61000-4-6	Conductive Susceptibility	150kHz-80MHz, 10V
IEC61000-4-11	Voltage Dips	

- RoHS

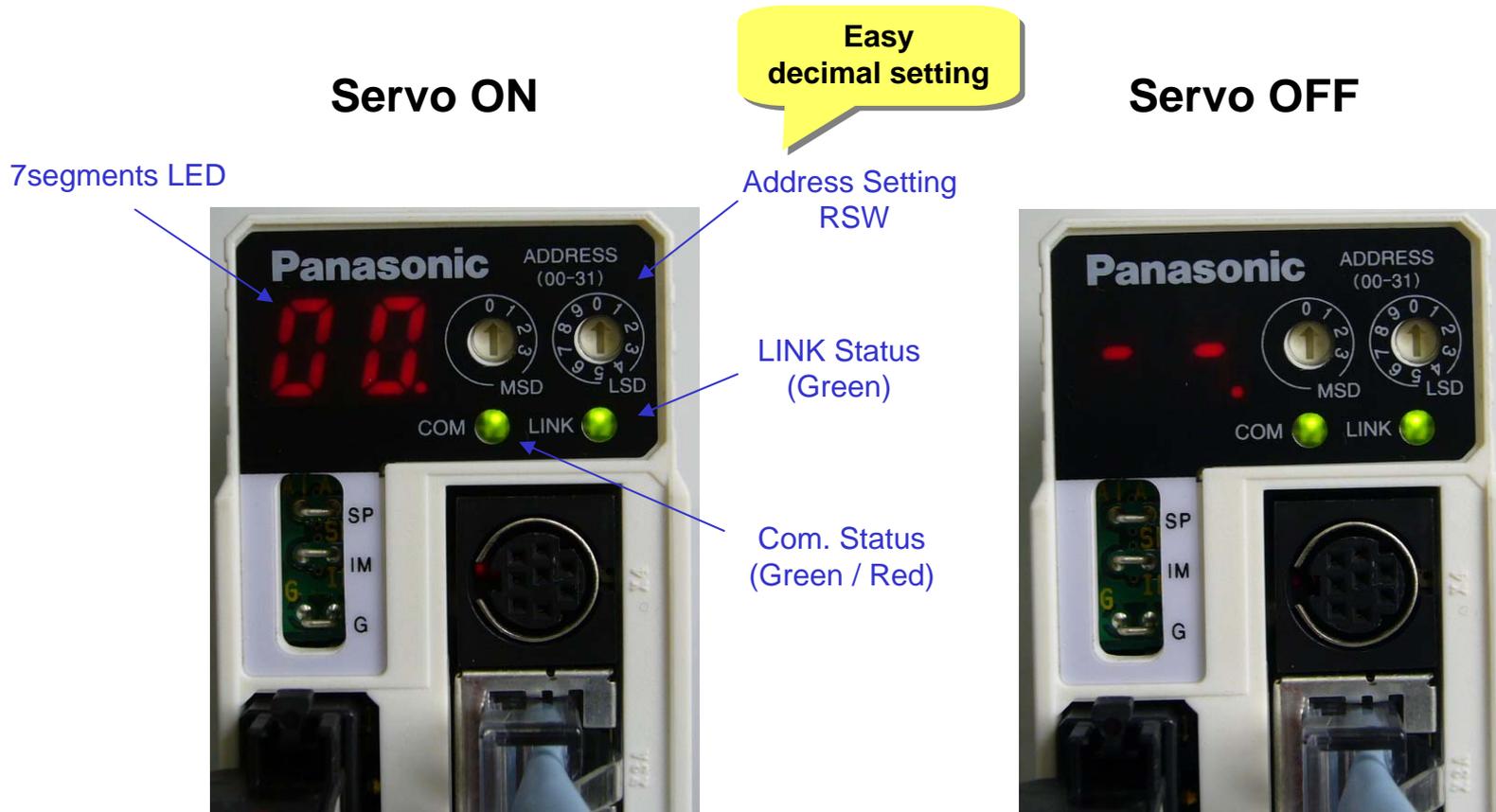


Appearance

Appearance



Front Panel



Note: If alarm, the error code is indicated on 7segments LED with blinking.

Appearance of Size A to D

A

B

C

D



W 40
H150
D132

W 55
H150
D132

W 65
H150
D172

W 85
H150
D172

A to C: Fan less
D or more: With built-in fan

Unit: mm

Lineup

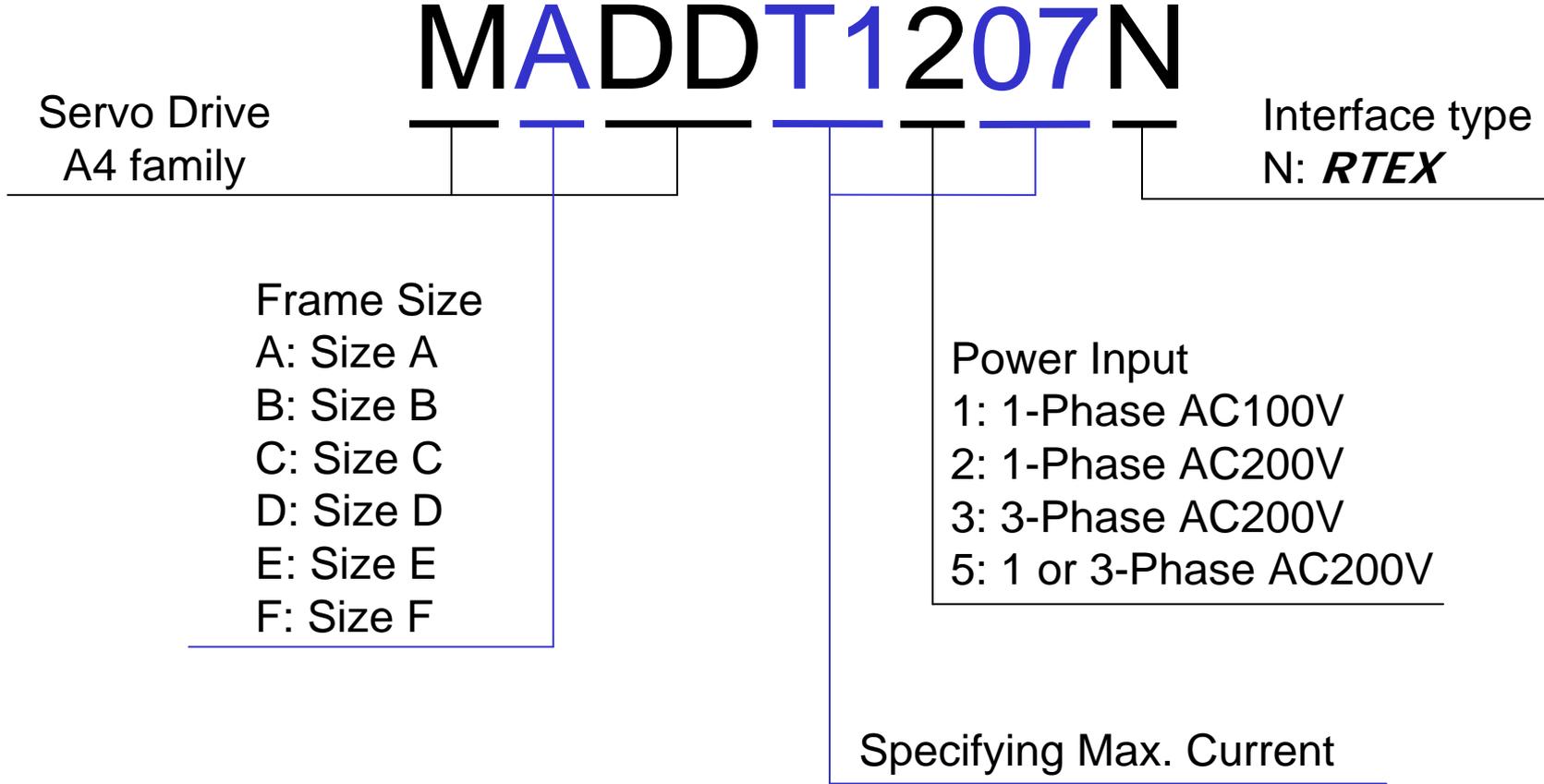
Rated Output of Motor

		50W	100W	200W	400W	750W	1kW	1.5kW	2kW	3kW	4kW	5kW	7.5kW
Power Input of Drive	1 Phase AC 100-115V	A	A	B	C								
		MADD T1105N	MADD T1107N	MBDD T2110N	MCDD T3120N								
	1 Phase AC 200-240V	A		A	B								
		MADD T1205N		MADD T1207N	MBDD T2210N								
1 or 3 Phase AC 200-240V					C	D							
					MCDD T3520N	MDDD T5540N							
3 Phase AC 200-230V								E	F	F		G	
								MEDD T7364N	MFDD TA390N	MFDD TB3A2N		MGDD TC3B4N	

Upper: Frame size

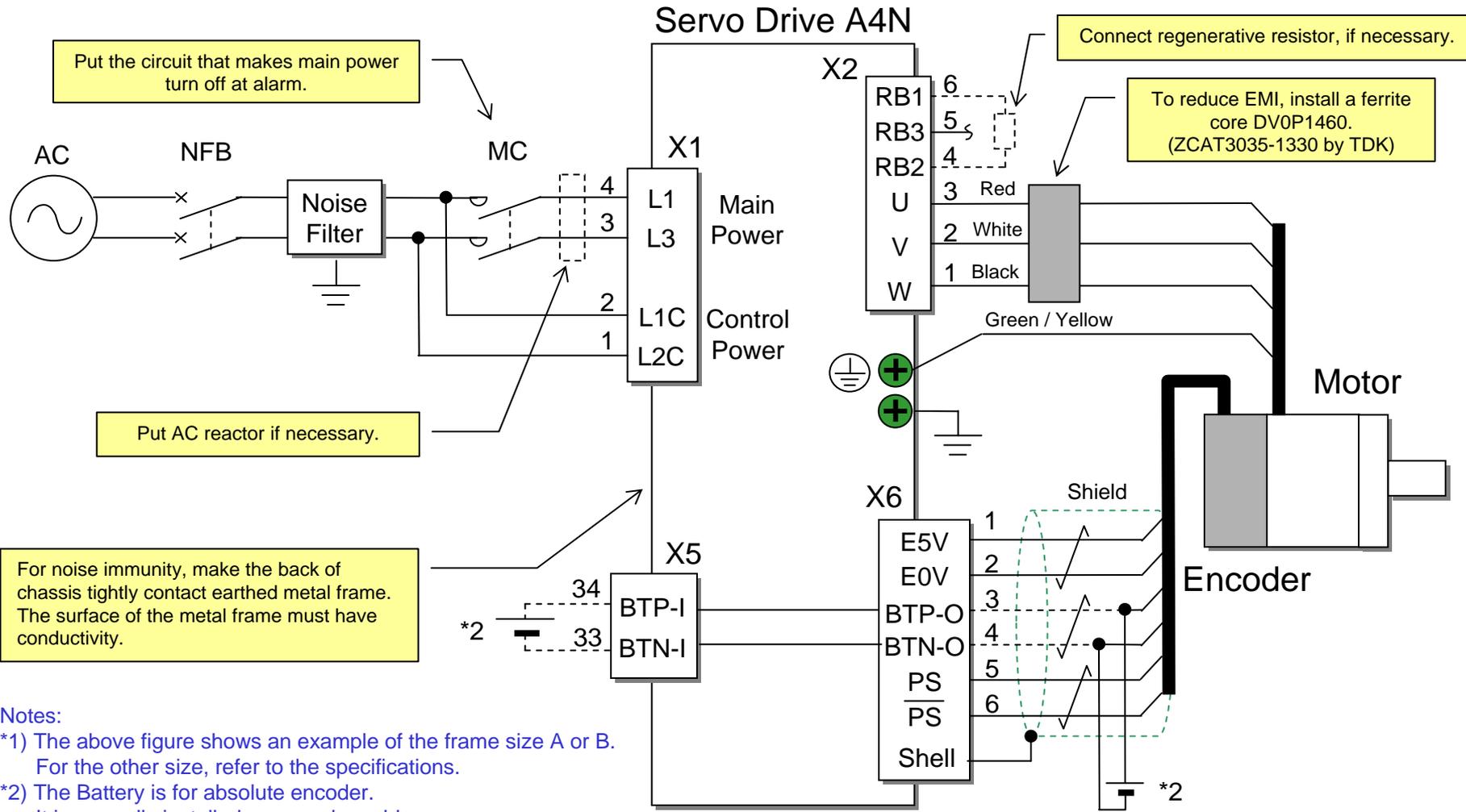
Lower: Typical model No. (Depending on combination with motor)

Structure of Model No.



Wiring

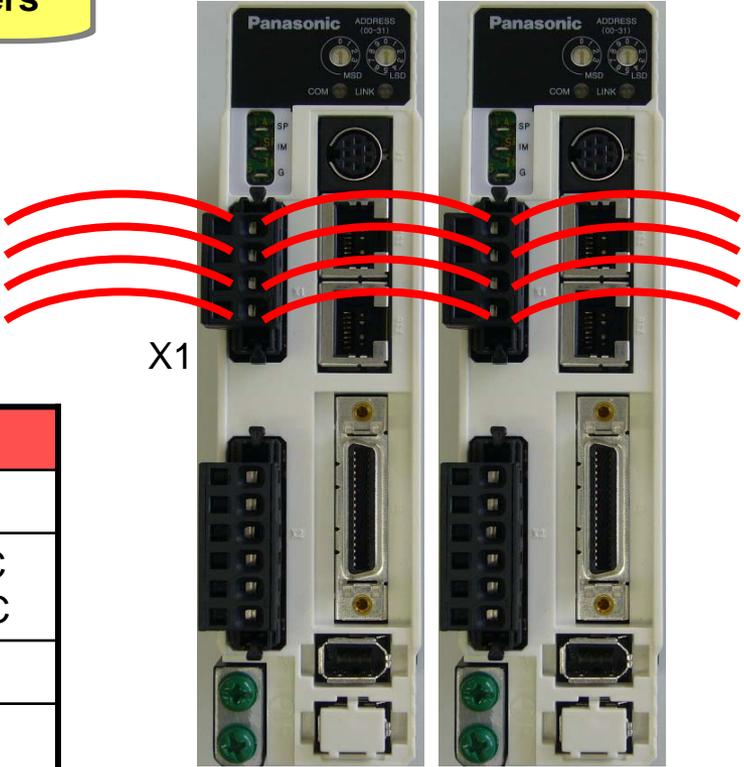
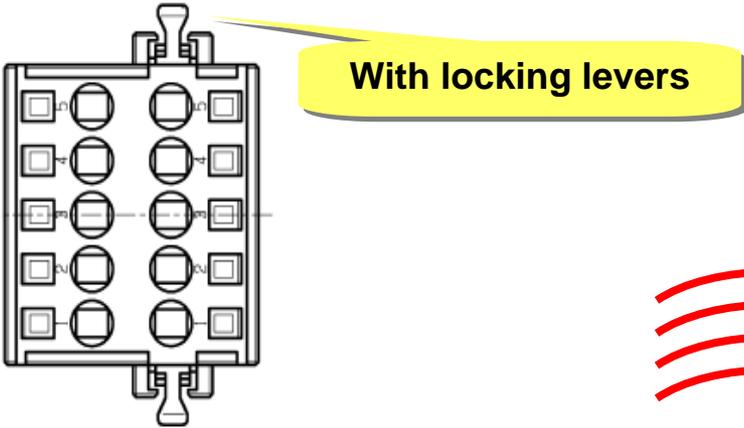
Power Supply and Motor



Notes:
 *1) The above figure shows an example of the frame size A or B. For the other size, refer to the specifications.
 *2) The Battery is for absolute encoder. It is normally installed on encoder cable, or alternatively can be also connected to X5 connector.

Daisy Chain of Power

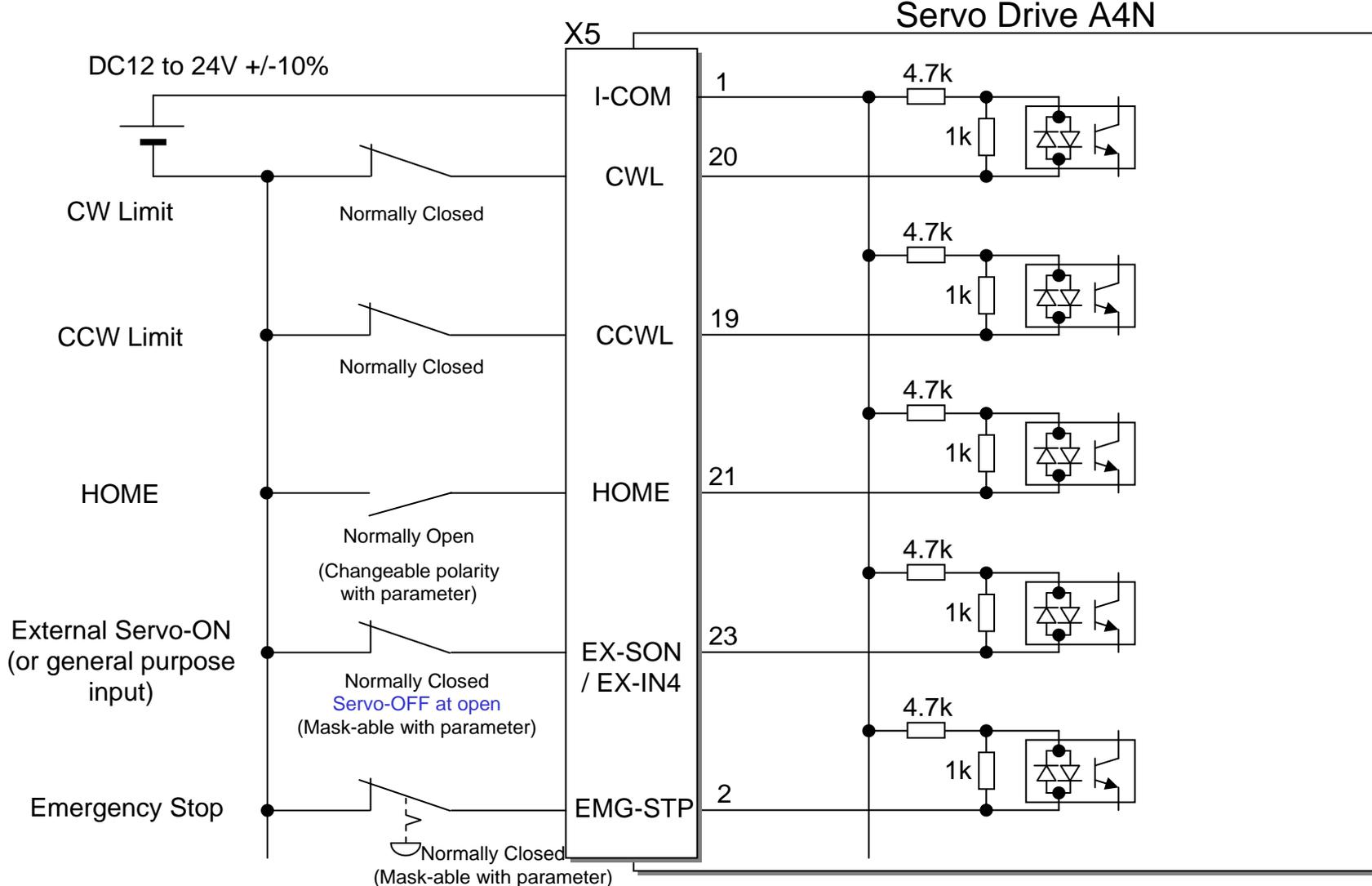
Using dual connector, Daisy Chain is possible.



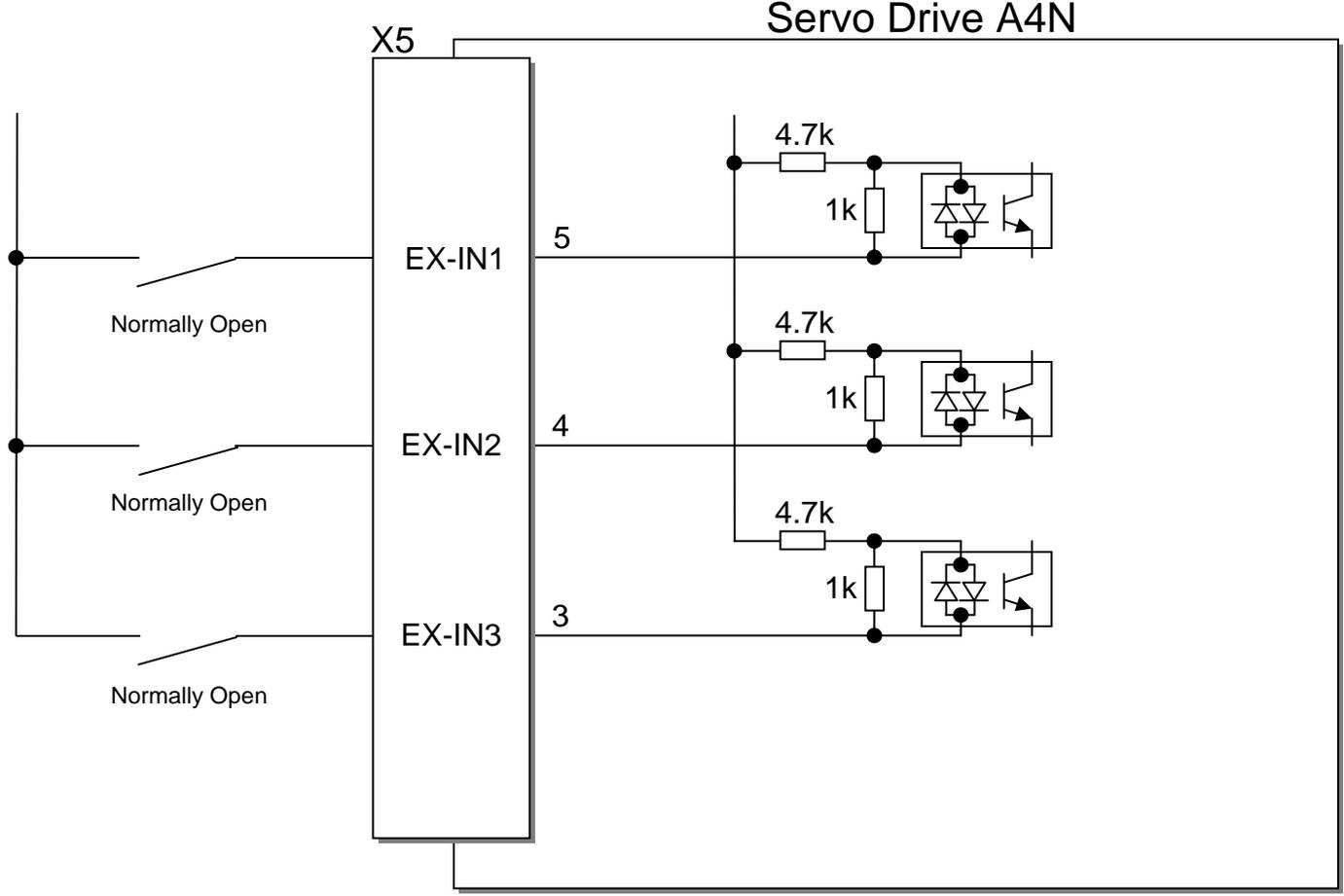
Specifications of connector:

	Description
Manufacturer	J.S.T. Mfg.
Model No.	4pole (for A, B size): 04JFAT-SAXGSA-C 5pole (for C, D size): 05JFAT-SAXGSA-C
Wire Size	AWG#14 to #18
Remark	This is not an accessory of the drive, so it is provided by yourself.

Sensor Inputs



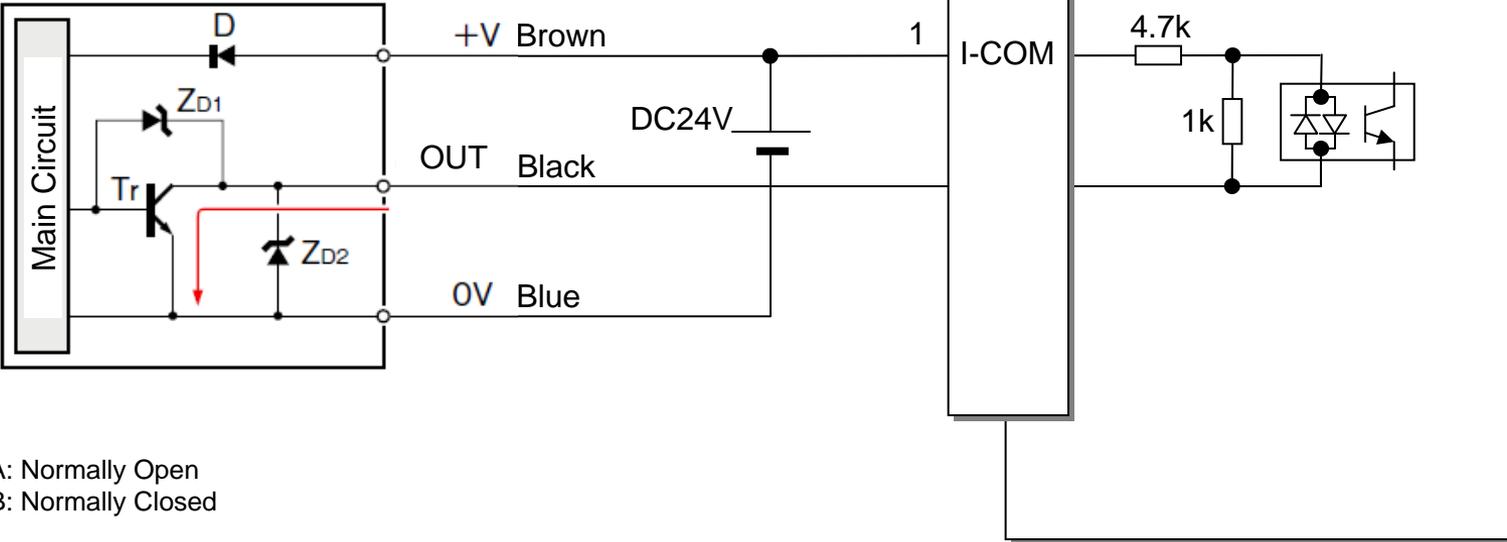
General Purpose Inputs



Note:
Host controller can monitor a state of EX-INs via RTEX.
These inputs do not influence servo control in the drive.

Sensor Input Example 1

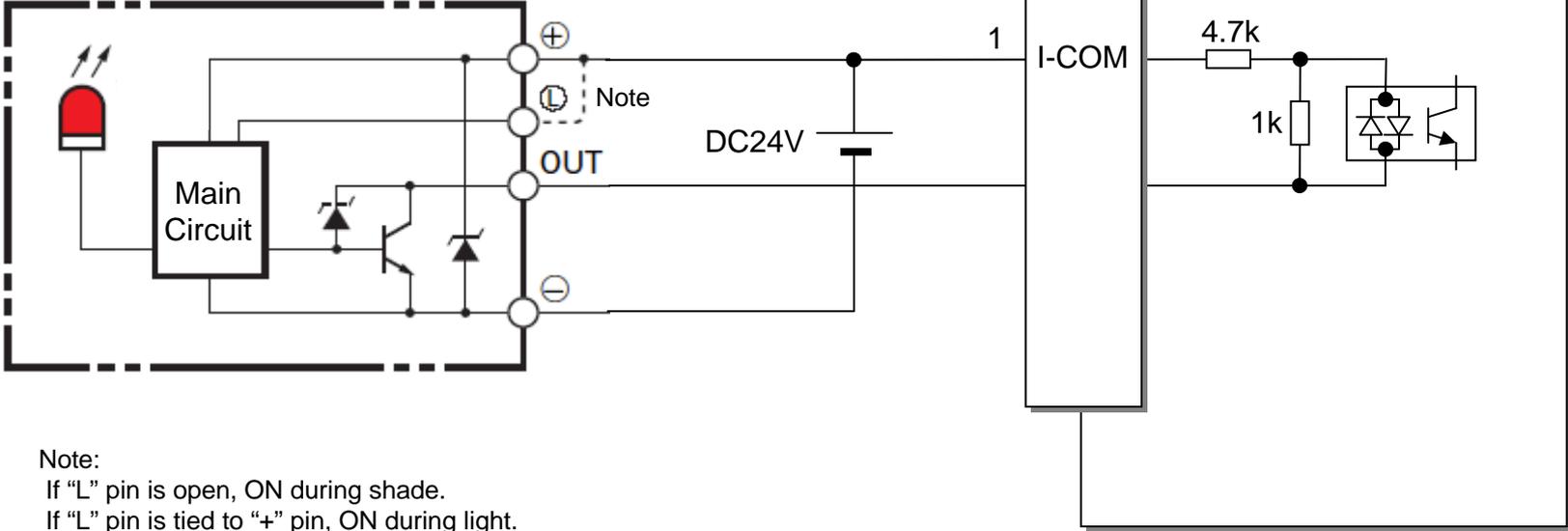
Proximity-Sensor by SUNX
GX-F12 (NPN transistor output)



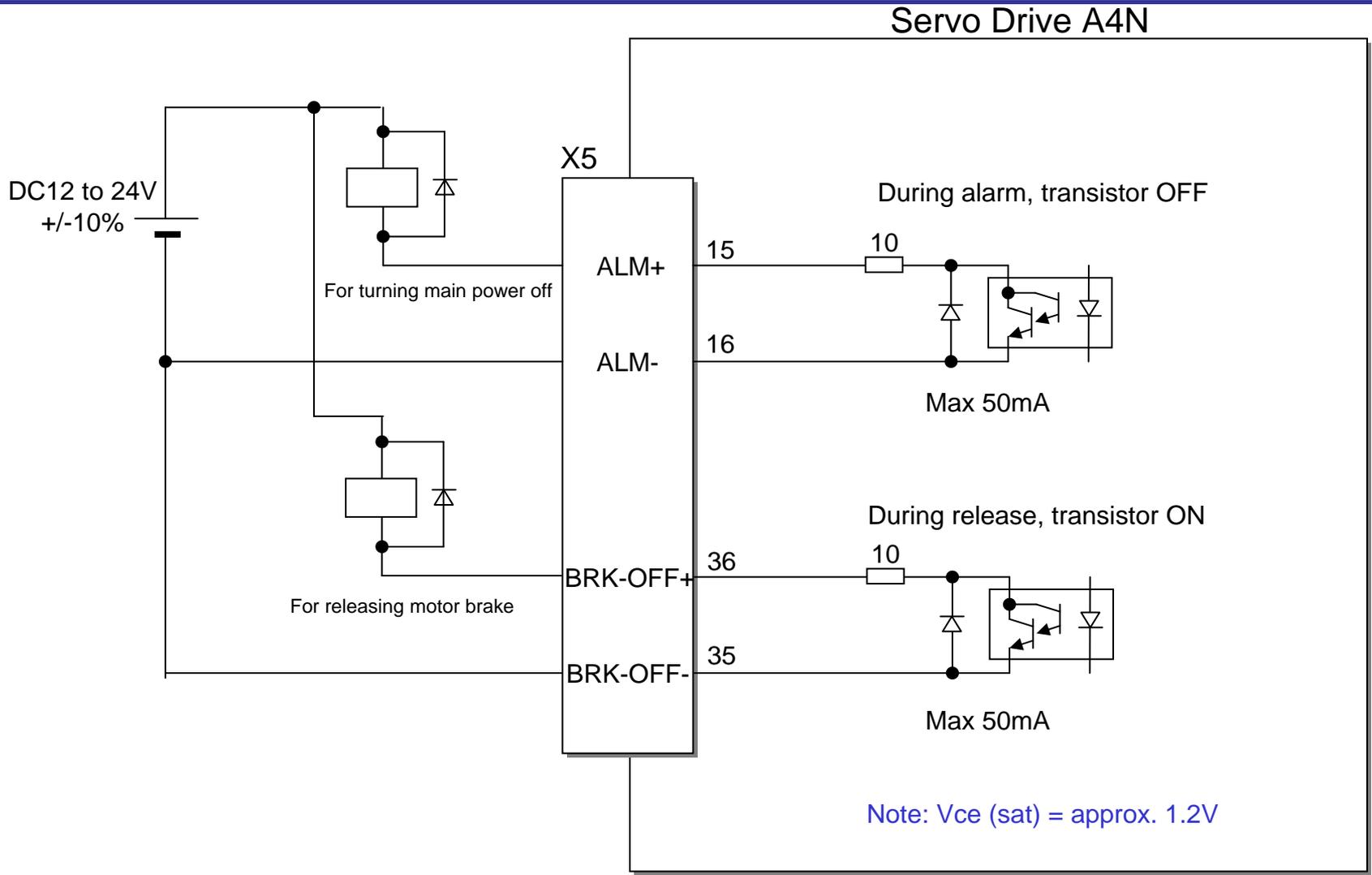
GX-F12A: Normally Open
GX-F12B: Normally Closed

Sensor Input Example 2

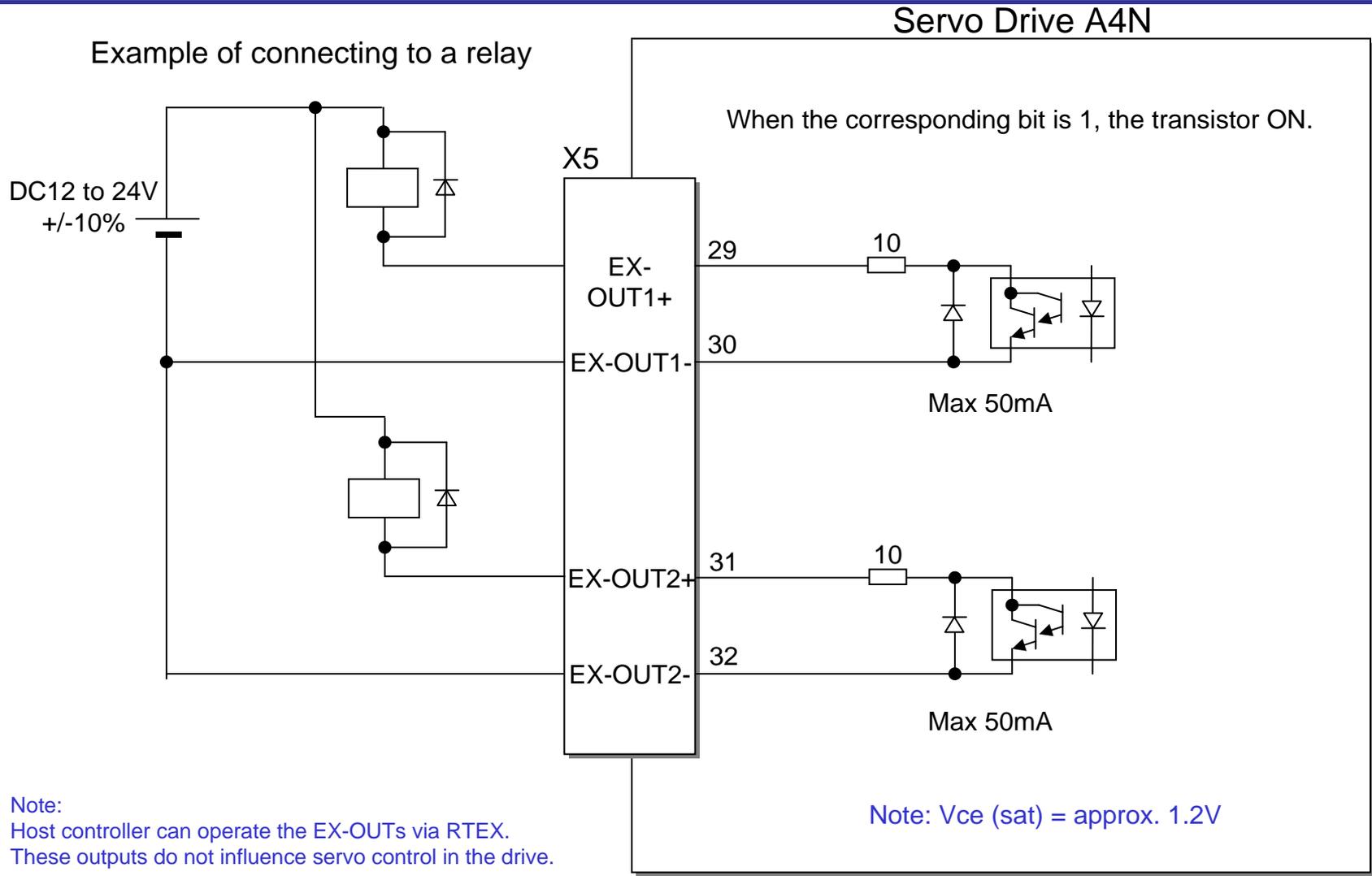
Photo-Sensor by OMRON
EE-SX672A (NPN transistor output)



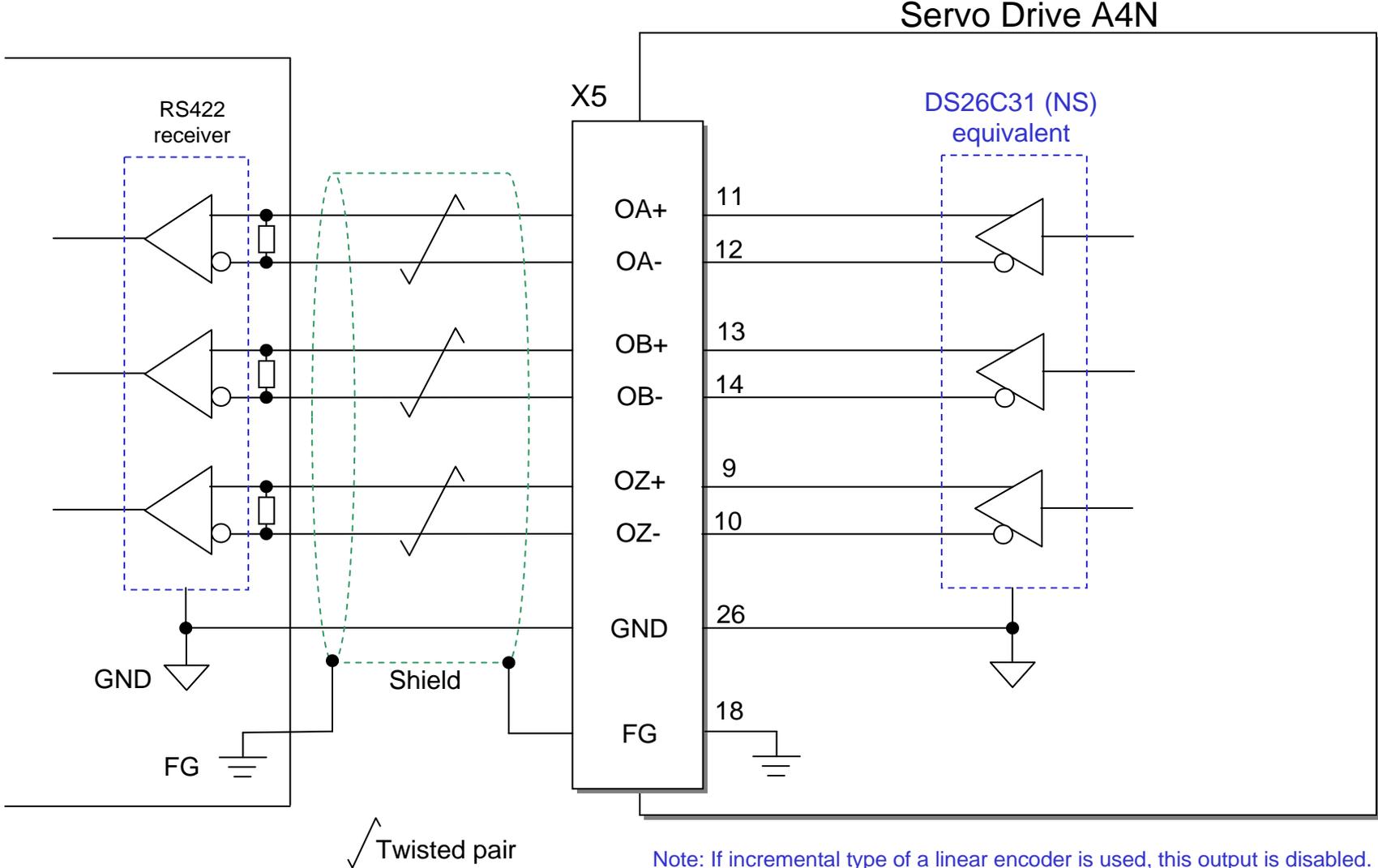
Relay Control Outputs



General Purpose Outputs

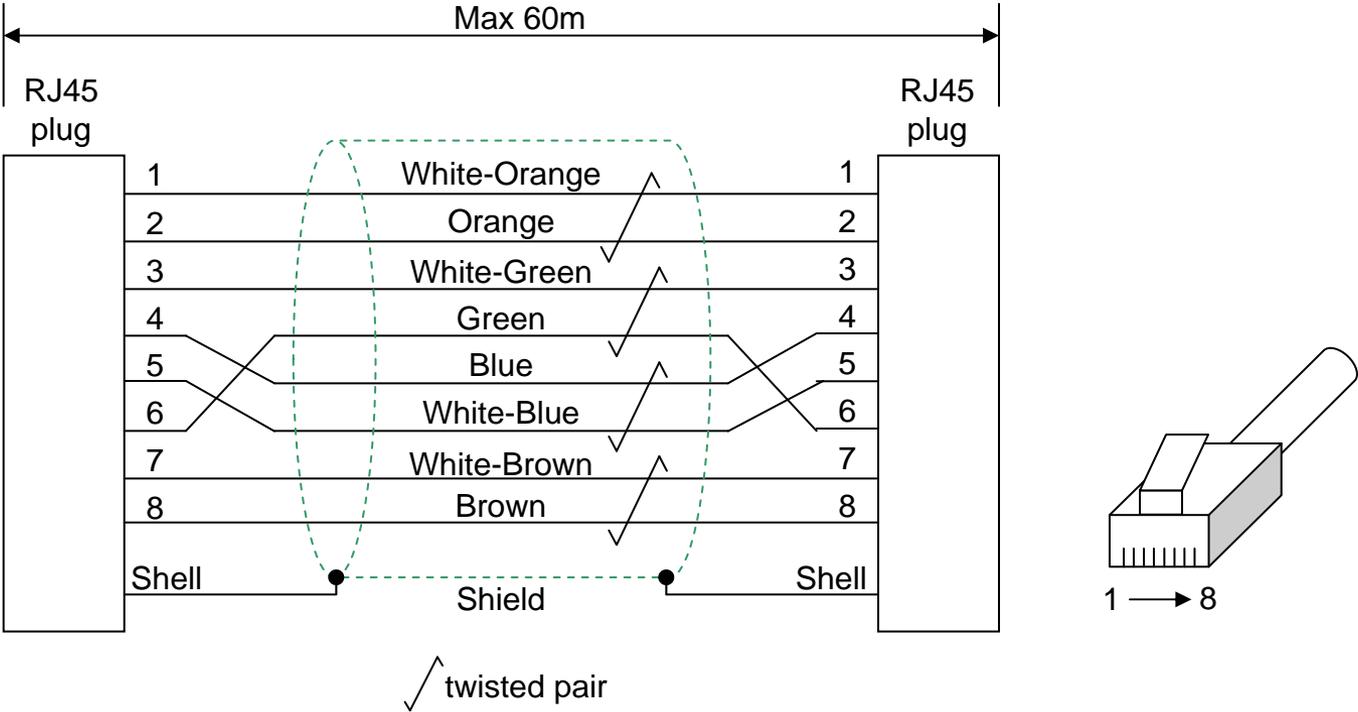


Encoder Signal Outputs



Wiring of Com. Cable (4pairs)

“Straight” Wiring

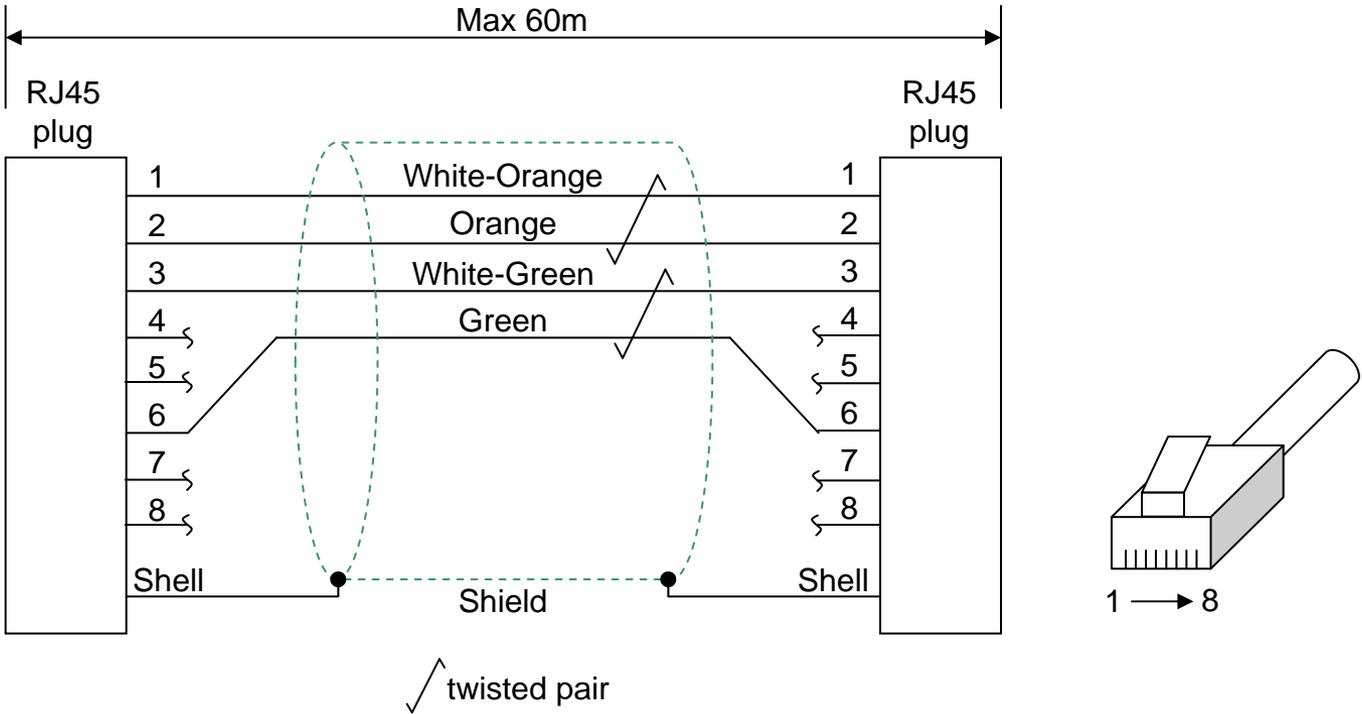


Notes:

- STP(Shielded Twisted Pair cable) conformed to category 5e or more must be used.
- Colors of the lead wire are defined by TIA/EIA-568B.
- A pair connected to 3-6pin is used as signal line.
- Unused 3 pairs must be also connected to 1-2, 4-5 and 7-8 as the above figure.

Wiring of Com. Cable (2pairs)

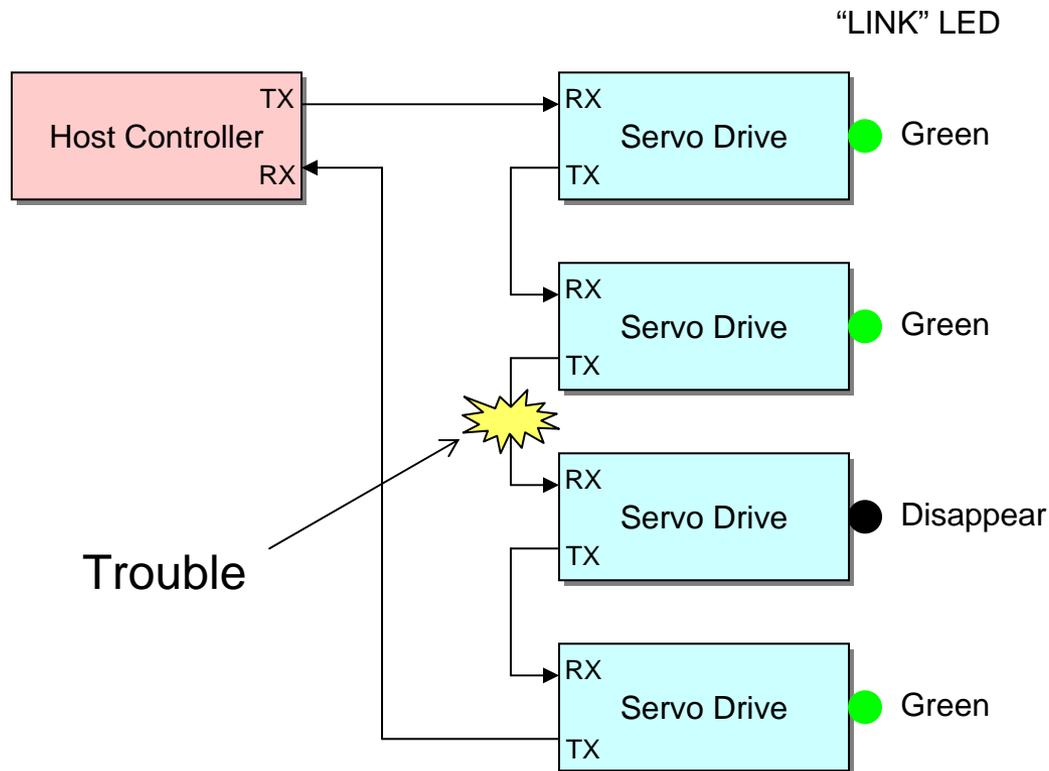
“Straight” Wiring



- Notes:
- STP(Shielded Twisted Pair cable) conformed to category 5e or more must be used.
 - Colors of the lead wire are defined by TIA/EIA-568B.
 - A pair connected to 3-6pin is used as signal line.
 - Unused 3 pairs must be also connected to 1-2 as the above figure.

Trouble of Com. Cable

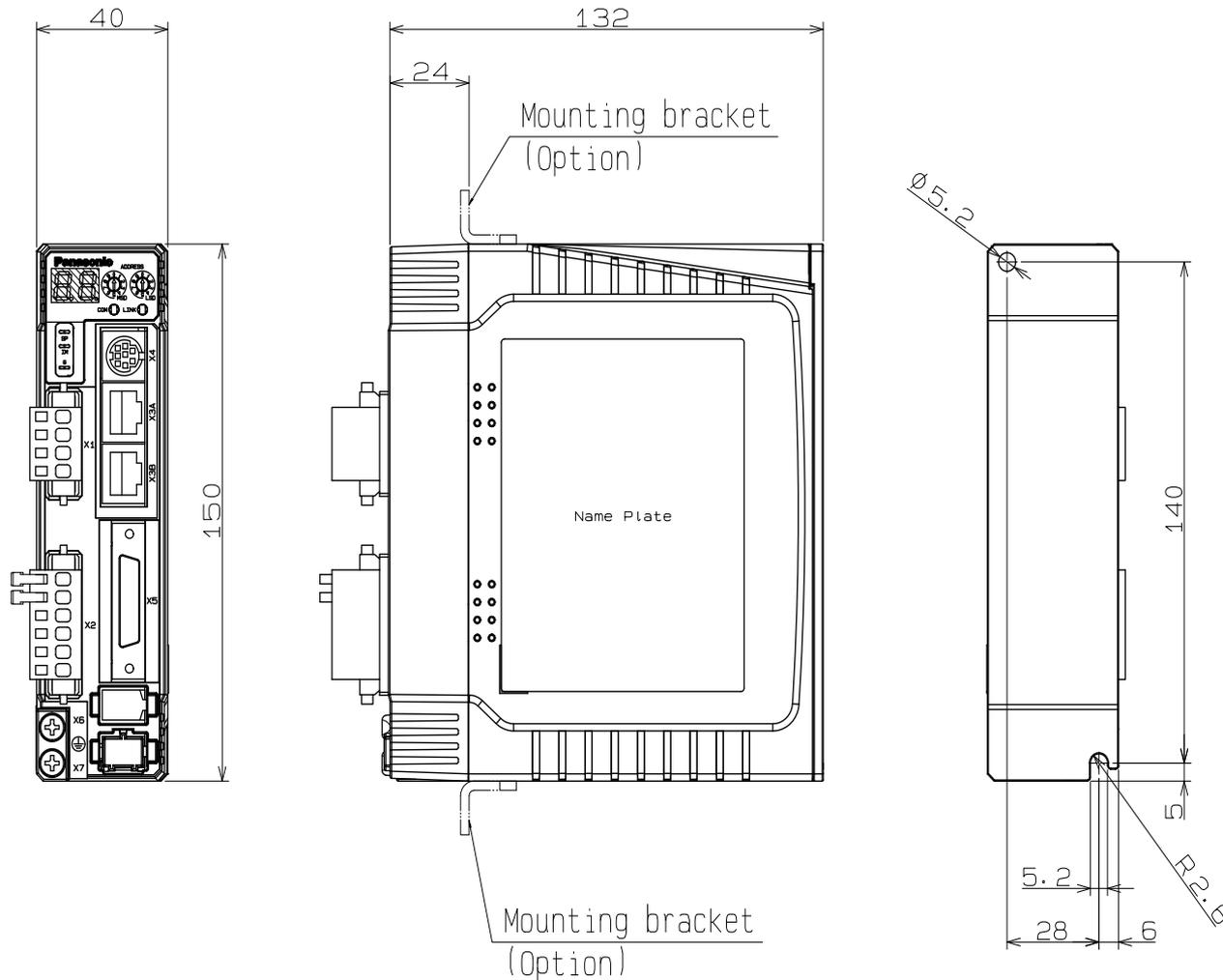
When “LINK” LED is disappear against power ON of all servos, make sure whether there is the trouble (e.g. breaking down) with a cable connected to RX of the disappearing servo.



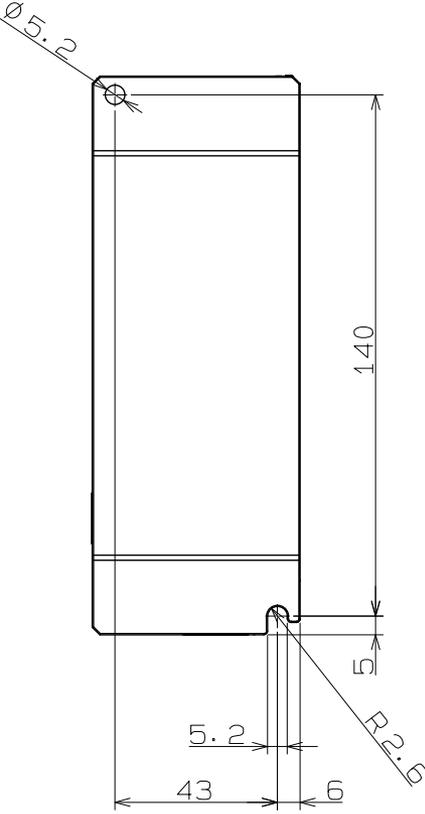
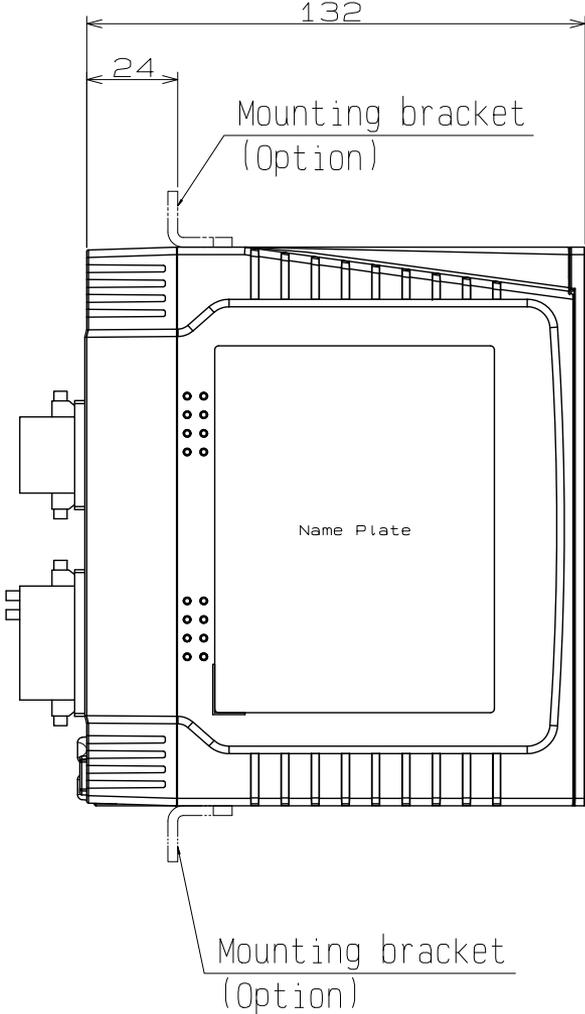
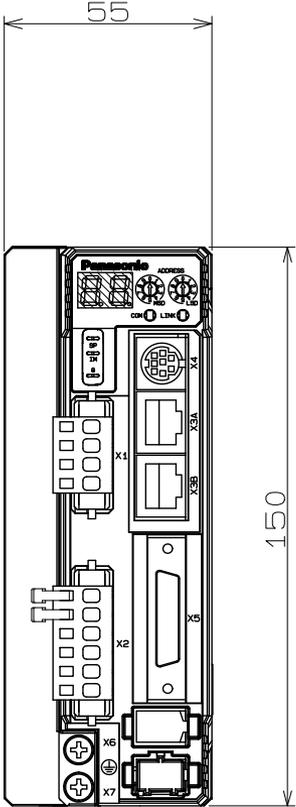
Dimensions

(unit: mm)

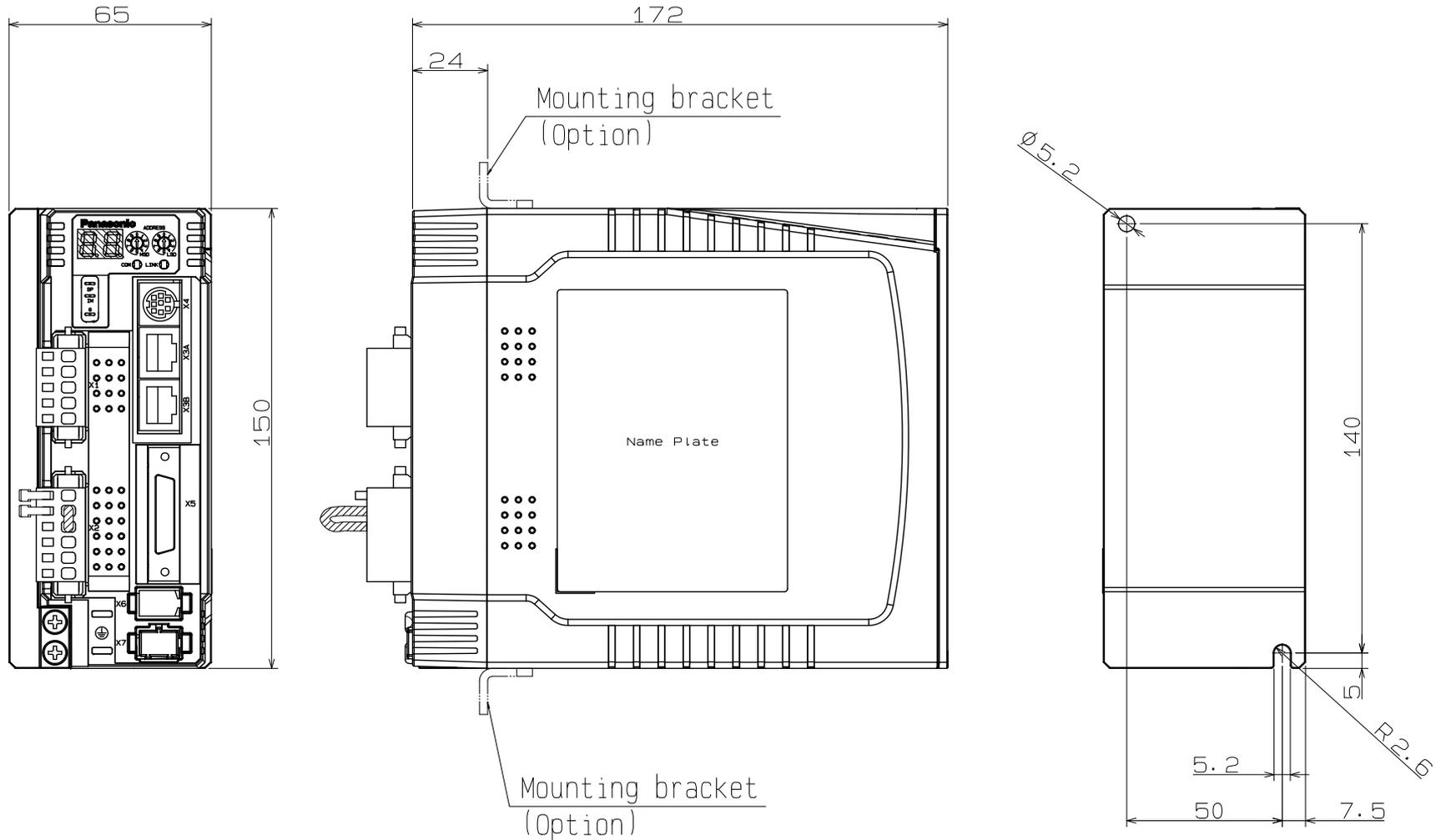
Size A



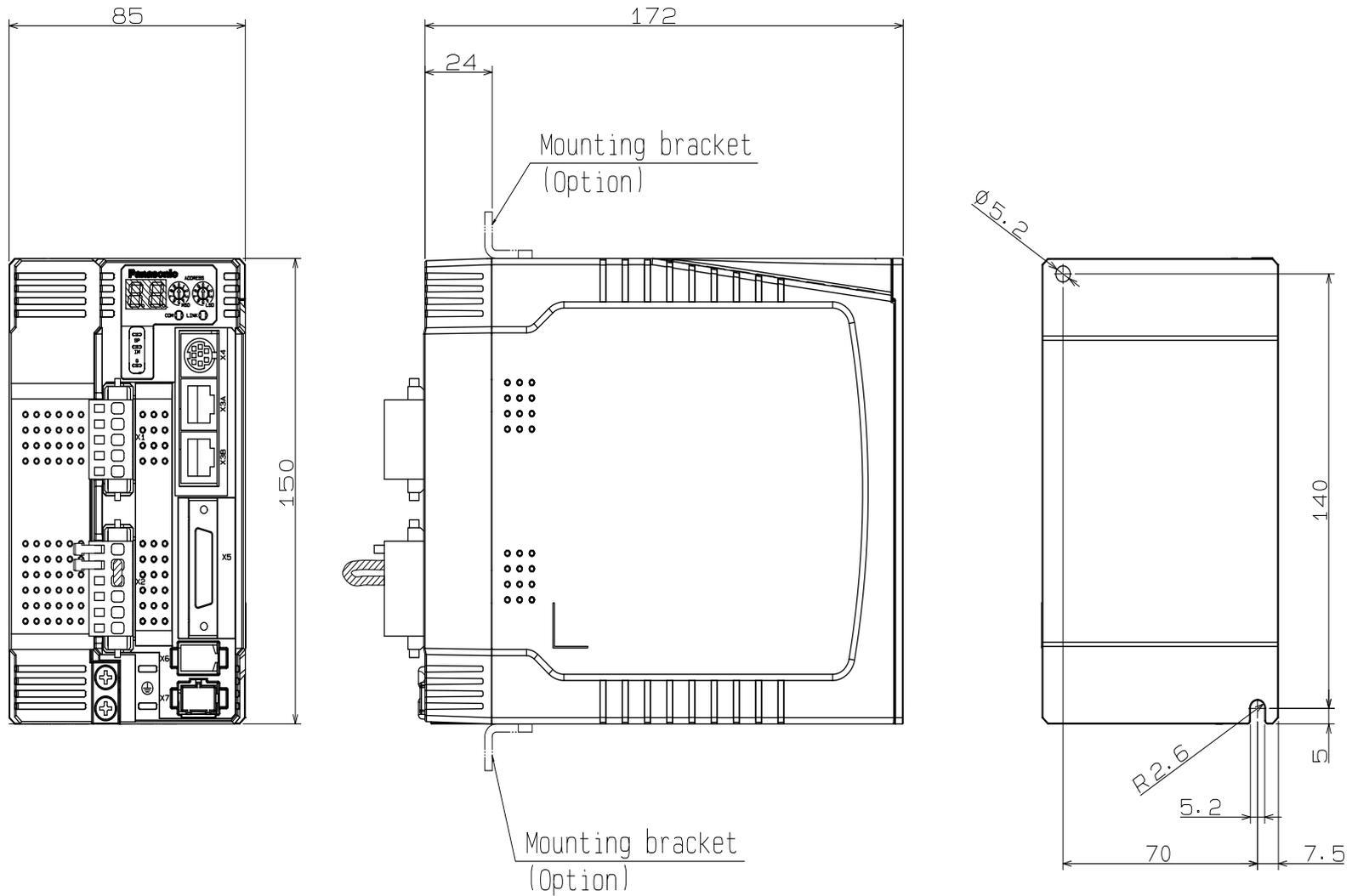
Size B



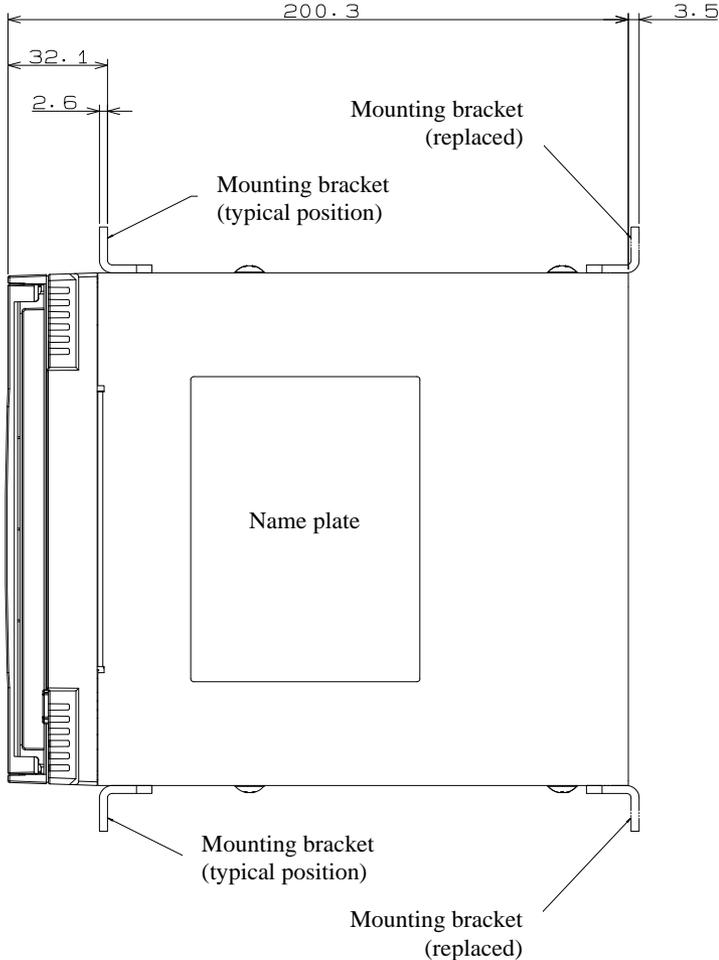
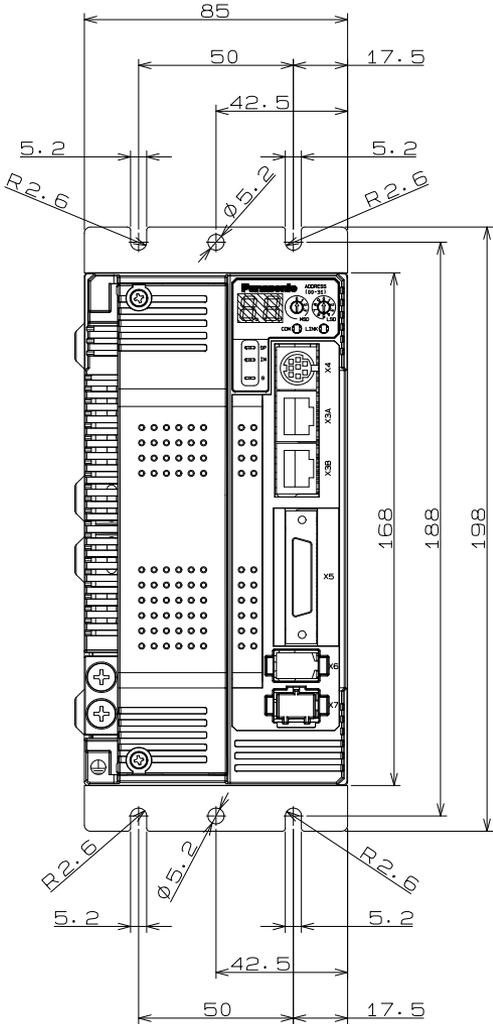
Size C



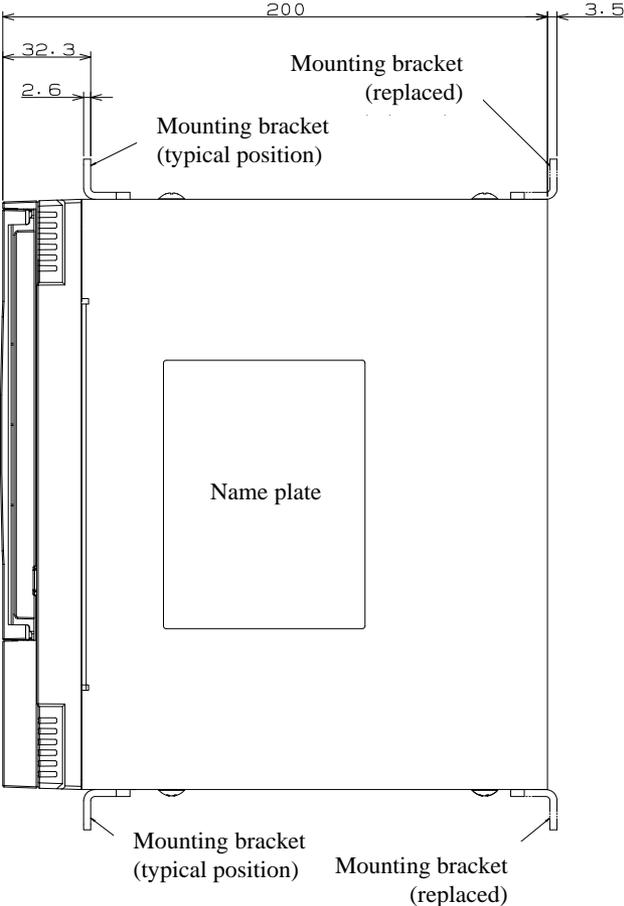
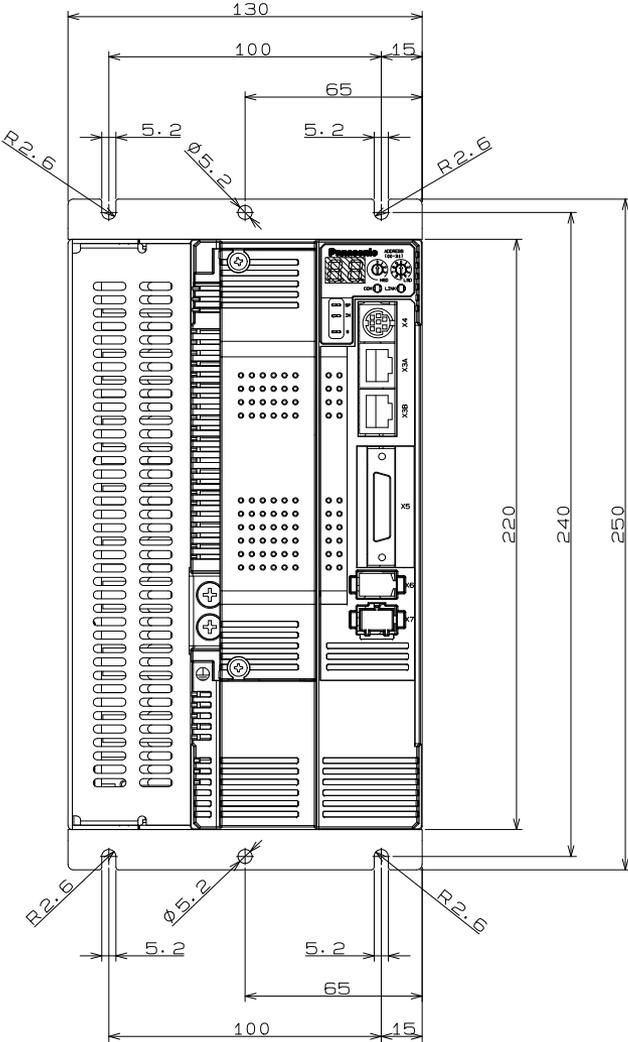
Size D



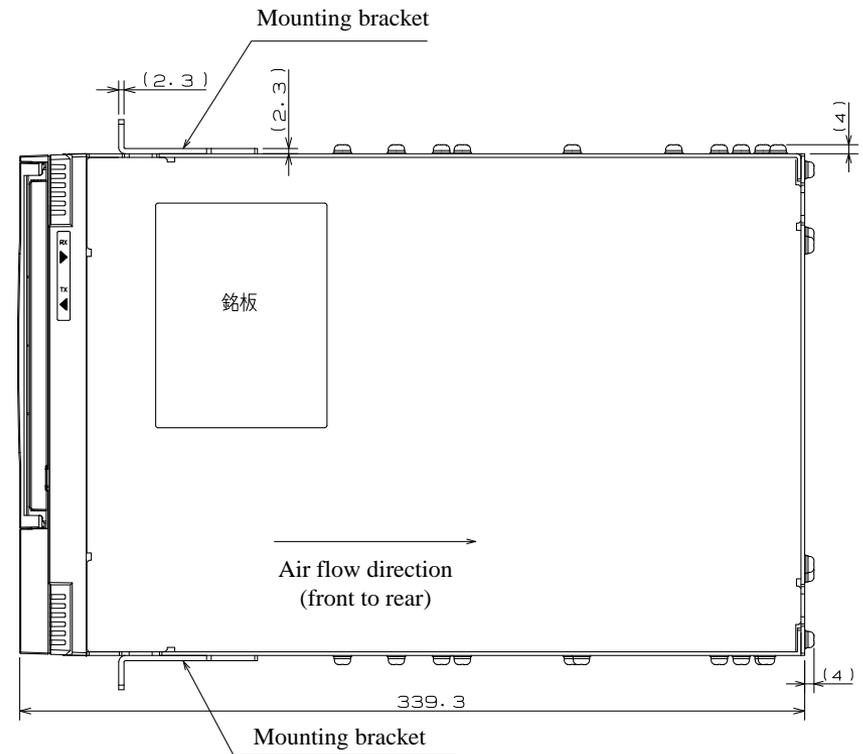
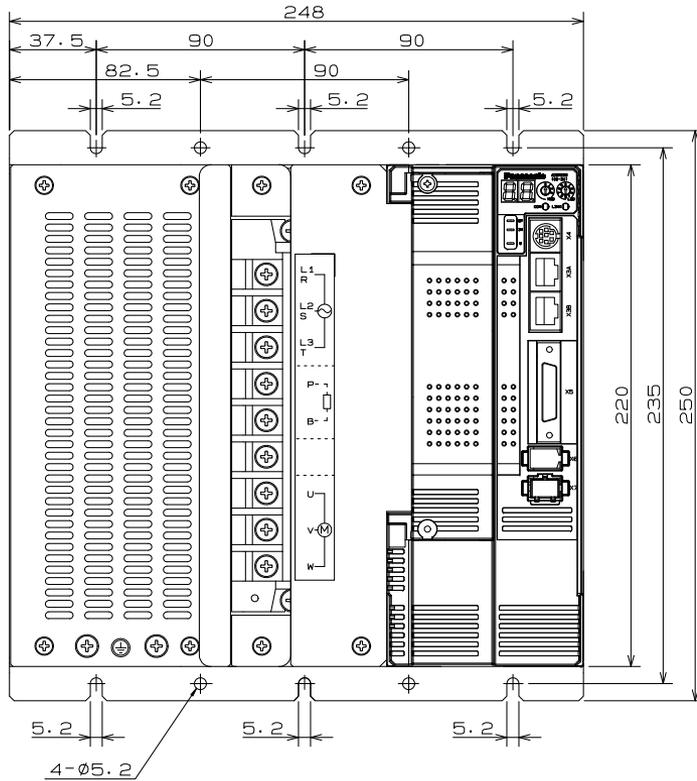
Size E



Size F



Size G



Options

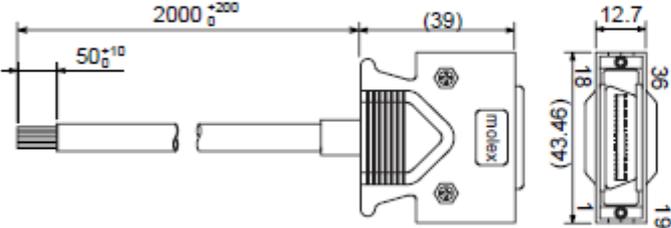
Cable and Connector

Except for X5 connector, the options are in common with A4.
For X5, the followings for A4P should be used.

X5 Cable

1) Model No. DV0P4510

2) Dimensions



<Remarks>
Color designation of the cable
e.g.) Pin-1 Cable color : Orange
(Red1) : One red dot on the cable

3) Table for wiring

Cable of 2m is connected.

Pin No.	color	Pin No.	color	Pin No.	color
1	Orange (Red1)	13	Gray (Red2)	25	White (Red3)
2	Orange (Black1)	14	Gray (Black2)	26	White (Black3)
3	Gray (Red1)	15	White (Red2)	27	Yellow (Red3)
4	White (Red1)	16	White (Black2)	28	Yellow (Black3)
5	White (Black1)	17	Yellow (Red2)	29	Pink (Red3)
6	Gray (Black1)	18	Yellow (Black2)	30	Pink (Black3)
7	Yellow (Red1)	19	Pink (Red2)	31	Orange (Red4)
8	Yellow (Black1)	20	Pink (Black2)	32	Orange (Black4)
9	Pink (Red1)	21	Orange (Red3)	33	Gray (Red4)
10	Pink (Black1)	22	Orange (Black3)	34	Gray (Black4)
11	Orange (Red2)	23	Gray (Red3)	35	White (Red4)
12	Orange (Black2)	24	Gray (Black3)	36	White (Black4)

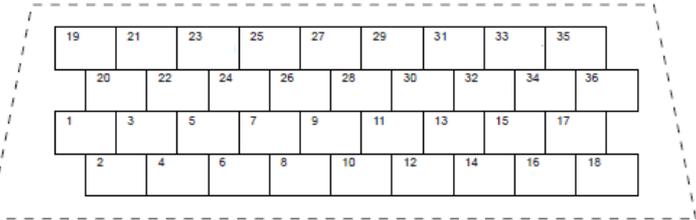
X5 Connector

1) Model No. DV0P4500

2) Components

Title	Part No.	Quantity	Manufacturer	Note
Connector	54306-3611 or 54306-3619 (lead-free)	1	Molex Inc.	For CN X5 (36-pins)
Connector cover	54331-0361	1		

3) Pin disposition (36 pins) (viewed from the soldering side)



X5 Pin Configurations

No.	Name
1	I-COM
2	EMG-STP
3	EX-IN3
4	EX-IN2
5	EX-IN1
6	Reserved
7	NC
8	NC
9	OZ+
10	OZ-
11	OA+
12	OA-
13	OB+
14	OB-
15	ALM+
16	ALM-
17	Reserved
18	FG

No.	Name
19	CCWL
20	CWL
21	HOME
22	Reserved
23	EX-SON / EX-IN4
24	Reserved
25	Reserved
26	GND
27	NC
28	NC
29	EX-OUT1+
30	EX-OUT1-
31	EX-OUT2+
32	EX-OUT2-
33	BTN-I
34	BTP-I
35	BRK-OFF-
36	BRK-OFF+

Note: Do not connect to "Reserved" or "NC".